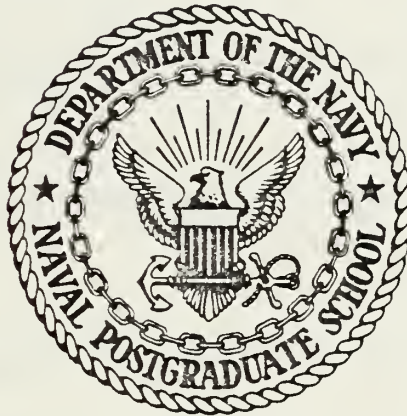


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NAVAL POSTGRADUATE SCHOOL

Monterey, California



THESIS

AN ANALYSIS OF
THREE APPROACHES TO THE HELICOPTER PRELIMINARY
DESIGN PROBLEM

by

Allen C. Hansen

March 1984

Thesis Advisor:

D. M. Layton

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An Analysis of
Three Approaches to the Helicopter Preliminary
Design Problem

by

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Lieutenant, United States Navy
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Submitted in partial fulfillment of the
requirements for the degree of

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Three methodologies from which to approach the problem of preliminary helicopter design are explored in this paper. The first is a sensitivity analysis of the basic helicopter performance equations. The purpose here is to ascertain where reasonable simplifications can be made that do not seriously degrade the accuracy of the results. The second is a graphical parametric design method, known as Carpet Plots. In this method a graphical solution is developed to meet the design criteria of the helicopter. In the third, an overview of Boeing Vertol's Helicopter Sizing and Performance Computer Program is given. The computer routines which enable a person to access HESCOMP on the Naval Postgraduate School main frame IBM system are also provided.

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I. INTRODUCTION

A. GENERAL

The helicopter design process, the subject of numerous articles and studies is an evolving discipline that borders on being an art. A successful design must balance the user's needs and desires against practical capabilities.

With the introduction of composite materials and new technologies, principally in rotor and engine performance, significant advances have been made in helicopter capabilities. In some instances, the performances of hybrid helicopter designs rivals that of a similarly sized conventional aircraft. For example, the YVX, a joint Boeing-Bell venture, will have the hover and low speed capabilities of a helicopter while being able to cruise at 300 knots.

Viable commercial and military helicopter designs are only thirty years old. The first major use of helicopters occurred during the Korean conflict. To put this in perspective, the first large scale use of conventional type aircraft was in World War I.

Helicopter design can proceed on a number of different levels, ranging from comprehensive computer design programs to preliminary analysis using simplifications of the basic performance equations. Each has its merit and place. Computer-aided design provides a great deal of data.

Generally, these programs integrate aircraft configuration sizing, performance and weight calculations in an iterative process. An example of a computer design program for helicopters is the Helicopter Sizing and Performance Computer Program [HESCOMP], originally developed by Boeing-Vertol for NASA. This program is currently used as a wide number of institutions conducting studies in helicopter design.

On the opposite end of the spectrum would be sensitivity design studies using the performance equations. Surprisingly accurate simplifications of these equations can be made. This provides the designer with an excellent method for doing first cut preliminary helicopter sizing at a low cost.

B. OBJECTIVE

This report is an investigation of several of the methods employed in the preliminary design of a helicopter. Conceptually, the report can be divided into three parts. In the first section, a sensitivity analysis of the basic performance equations is performed. The purpose here is to ascertain where reasonable simplifications can be made that do not seriously degrade the accuracy of the result.

In the second section a graphical method of doing parametric design studies, known as Carpet Plots, is developed. This method allows the user to formulate a graphical solution matrix to meet the design criteria specified for the helicopter. Carpet Plots are

particularly instructive since they give visual insight into the interplay of the various design parameters.

In the last section, an overview of HESCOMP is given. Programs are developed which enable a person to access HESCOMP on the Naval Postgraduate School Main Frame IBM system.

II. SENSITIVITY ANALYSES OF BASIC HELICOPTER EQUATIONS

A. DESCRIPTION OF PROBLEM

In preliminary helicopter design, there are a number of instances where a quick first cut analysis would be extremely helpful. This is especially true in determining the preliminary size of the helicopter required to meet the specifications.

Historically, there are a number of variables in the performance equations of helicopters which may be treated as constants. This may allow for significant simplifications and aid in the preliminary design process.

In this section, a sensitivity analysis of the performance equations is done. In a sensitivity analysis, each parameter [or variable] is varied in order to determine its effect on the equation. Variables which are shown to have little effect may be treated as constants and the equation simplified accordingly.

B. SOLIDITY

Solidity, σ , is the fraction of the disk area that is composed of blades. It is a function of b , the number of blades, of a constant cord, c , at a radius, R :

$$\sigma = \frac{bc}{\pi R} \quad (2.1)$$

C. DISK LOADING:

Disk loading is defined as the ratio of the weight to the total area of the rotor disk.

$$\begin{aligned} DL &= \frac{\text{WEIGHT}}{\text{AREA}} \\ &= \frac{W}{A} = \frac{W}{\pi R^2} \text{ [lb/ft}^2\text{]} \end{aligned} \quad (2.2)$$

D. POWER LOADING

Power loading is the ratio of weight to input power.

$$PL = \frac{W}{P_{in}} \text{ [lb/hp]} \quad (2.3)$$

In a hover, thrust equals weight; this allows us to rewrite the power loading for the hover condition as

$$PL = \frac{T}{P_{in}} = \frac{\text{ROTOR THRUST}}{\text{ROTOR HORSEPOWER}} \text{ [lb/hp]} \quad (2.4)$$

E. COEFFICIENT OF THRUST AND POWER

The coefficient of thrust, C_T , is a non-dimensional coefficient which facilitates computations and comparisons:

$$C_T = \frac{T}{A \rho V_T^2} = \frac{T}{\pi R^2 \rho (\Omega R)^2} \quad (2.5)$$

Similarly, a coefficient of power, C_p , has been established as:

$$C_P = \frac{P}{A\rho V_T^3} = \frac{P}{\pi R^2 \rho (\Omega R)^3} \quad (2.6)$$

No significant simplifications can be made to either of these coefficients. However, it should be observed that the coefficient of thrust is inversely proportional to the square of the rotor tip velocity, while the coefficient of power is inversely proportional to the cube.

Assuming all other factors being equal, increasing the rotor tip velocity from 600 fps to 700 fps [an increase of 16.7 percent] will have the following result on these coefficients.

$$\begin{aligned} C_T &= \frac{T}{A\rho V_T^2} \\ &= \frac{T}{A\rho (1.167)^2} \\ &= \frac{T}{A\rho (1.361)} \end{aligned} \quad (2.5)$$

The coefficient of thrust is reduced by 26.9 percent. Similarly, for the coefficient of power:

$$\begin{aligned}
C_P &= \frac{P}{A\rho V_T^3} \\
&= \frac{P}{A\rho (1.167)^3} \\
&= \frac{P}{A\rho (1.589)}
\end{aligned}
\tag{2.6}$$

The coefficient of power is reduced by 37.1 percent.

F. HOVER POWER

The total power in a hover is made up of two terms, profile power, P_o , and induced power, P_i .

Utilizing black element theory the profile power required to hover can be expressed as:

$$P_o = \frac{1}{8} \sigma_r \bar{C}_{do} \rho A(\Omega R)^3 \tag{2.7}$$

The induced power predicted by momentum theory is:

$$\begin{aligned}
P_i &= V_{in} T \\
&= \frac{T^{3/2}}{\sqrt{2\pi\rho R^2}}
\end{aligned}
\tag{2.8}$$

The total power required to hover is:

$$P_T = P_i + P_o \tag{2.9}$$

$$P_T = \frac{T^{3/2}}{\sqrt{2\pi\rho R^2}} + \frac{1}{8} \sigma_r \bar{C}_{do} \rho A(\Omega R)^3 \quad (2.10)$$

Donald M. Layton in Helicopter Performance, [Ref. 1], found that for the optimum hover power, the induced power is equal to twice the profile power. The analysis was performed in the following manner.

By assuming constant weight, density, solidity, and an average profile drag coefficient, as well as a fixed rotational velocity, equation (2.10) reduces to

$$P = \frac{C_1}{R} + C_2 R^2 \quad (2.11)$$

where C_1 and C_2 are constants.

As equation (2.12) shows, profile power increases as the square of the blade radius while the induced power decreases with increasing blade radius.

The optimum hover power with respect to rotor radius can be determined by taking the differential and setting it equal to zero.

$$\frac{dP}{dR} = 0 = -\frac{C_1}{R^2} + 2 C_2 R \quad (2.12A)$$

$$\text{or} \quad \frac{C_1}{R} = 2 C_2 R^2 \quad (2.12B)$$

$$\text{which implies} \quad P_i = 2 P_o \quad (2.12C)$$

G. HELICOPTER SIZING

A simplified relationship between the total power required, gross weight and rotor radius can be developed in the following manner.

The total power required to hover equation for the main rotor was developed in the preceding section and is repeated here for clarity.

$$P_T = P_i + P_o \quad (2.9)$$

$$P_T = \frac{T^{3/2}}{\sqrt{2\pi\rho}} \cdot \frac{1}{R} + \frac{1}{8} \sigma_r \bar{C}_{do} \rho \pi V_{tip}^3 R^2 \quad (2.10)$$

In a hover, thrust equals weight. Solving equation (2.11) for weight one obtains:

$$W^{3/2} = [P_T - \frac{1}{8} \sigma C_{do} \rho \pi V_T^3 R^2] \sqrt{\rho A} \quad (2.13)$$

This equation may be further simplified if it is assumed that the density, average profile drag coefficient and tip velocity are constants; these are reasonable assumptions. Historically, the average profile drag coefficient of a helicopter has been approximately 0.01. The operating environment of today's helicopters, especially military, is below 5,000 feet agl. This allows for the use of the standard sea level value for density with little error. Primarily, due to tip mach effects, the upper limit on the rotor tip velocity is in the range of 700 fps.

The resulting equation with these assumptions incorporated into a constant, K , is:

$$W = [47.527 P_T R - K_1 bc]^{2/3} \quad (2.13)$$

Equation (2.13) can be further reduced when the order of magnitude of the two terms is considered.

$$47.527 P_T R \gg K_1 bc$$

Thus,

$$W \approx [47.527 P_T R]^{2/3} \quad (2.14)$$

To determine how accurate this simplification is, the equation is used to approximate the total weight of a number of helicopters for which the parameters are available. As Table 2.1 indicates, the weight approximation formula yields values within six percent of the actual total weight of these helicopters.

H. FIGURE OF MERIT

A figure of merit, FM , has been defined for the helicopter as the ratio of the ideal rotor induced power to the actual power required to hover, with non-uniform induced velocity, tip losses and profile drag power.

TABLE 2.1

HELICOPTER WEIGHT COMPARISON

HELICOPTER	TOTAL GROSS WEIGHT (1000 lbs)	CALCULATED GROSS WEIGHT (1000 lbs)	PERCENT OF ACTUAL GROSS WEIGHT
AH-64	14.66	14.69	101%
UH-1N	14.20	13.74	97%
H-3H	21.00	20.63	98%
S76	10.00	9.90	99%
UH-60A	20.25	19.33	95%
H-54B	42.00	42.00	100%
H-53D	42.00	41.00	98%
H-53E	73.50	69.00	84%

In a hover, the figure of merit may be written as:

$$\begin{aligned} FM &= \frac{1}{\sqrt{2}} \cdot PL \cdot \frac{DL}{\sqrt{\rho}} \\ &= \frac{CT^{1.5}}{\sqrt{2C_p}} \end{aligned} \quad (2.15)$$

The figure of merit is customarily plotted against the quantity CT/σ . According to Zalesch [Ref. 2], CT/σ , is proportional to the average blade angle of attack and can be used as a measure of rotor efficiency. The curve in Figure 2.1 is based on data from Reference 2 for a typical tail rotor helicopter.

Main Rotor Hover Performance

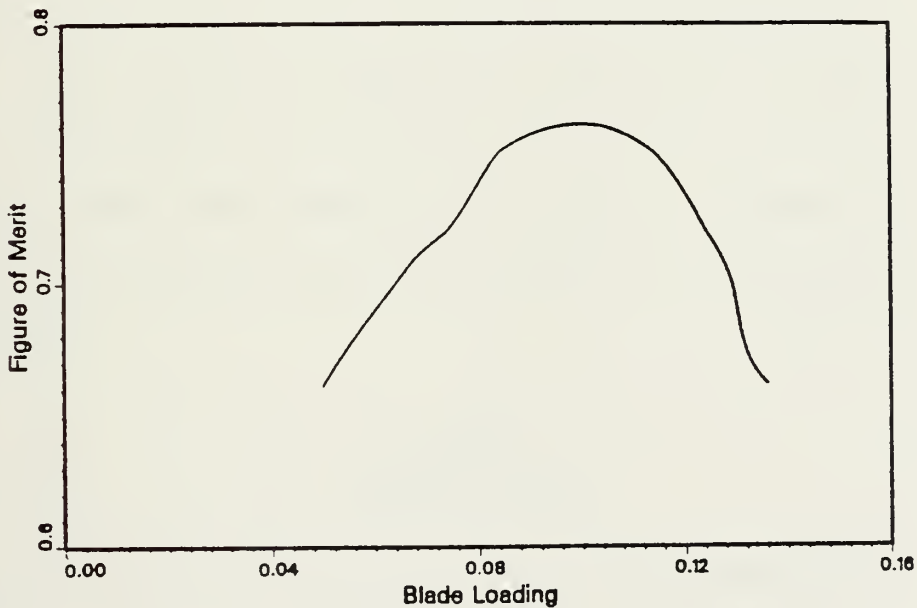


Figure 2.1. FM Versus Blade Loading CT/σ

Previous studies have shown that a figure of merit between 0.70 and 0.80 is considered average.[Ref. 3] If the induced power is between 70 and 80 percent of the total power, the figure of merit will be approximately 0.75.

With the figure of merit limited to values between 0.70 and 0.80, the following simplification can be made, assuming the hover condition of thrust equaling weight and standard sea level conditions:

$$FM = \frac{W^{3/2}}{67.214 P_T R} \quad (2.16)$$

For Navy helicopter design, the rotor radius has been limited by flight deck spotting constraints to less than 30 feet; the exception to this is the H-3, R = 31 feet and the H-53, R = 36 to 38 feet [depending on the model]. However, these two helicopters work almost exclusively from large air dedicated ships such as the LPH, LHA and CV.

If the small deck operating assumption is made, equation (2.16) can be further simplified to [assuming R = 28 feet]:

$$P = \frac{W^{3/2}}{1881.98 FM} \quad (2.17)$$

An FM of 0.80 will yield a P to W relationship of:

$$P_T = \frac{W^{3/2}}{1505.58} \quad (2.18)$$

while an M of 0.70 yields a relationship

$$P = \frac{W^{3/2}}{1317.39} \quad (2.19)$$

If equation (2.17) is solved utilizing the approximate weight relationship developed earlier of

$$W^{3/2} = 47.527 P_T R \quad (2.14)$$

a value for the figure of merit of 0.707 is obtained. This is within the historical range of values.

I. TAIL ROTOR SIZING

A historical analysis of typical helicopters [Ref. 3], shows the following empirical relationship for the tail rotor radius

$$R_T \simeq 1.3 \left[\frac{GW}{1000} \right]^{1/2} \text{ [ft]} \quad (2.20)$$

when comparing the results of this equation with actual tail rotor radius data, it was found that if a multiplication factor of 1.2 is used vice 1.3 a better approximation is obtained. The results are tabulated in Table 2.2.

J. FORWARD FLIGHT POWER CONSIDERATIONS

The total power in forward flight consists of induced, profile and parasite power. If the helicopter is a single rotor vehicle, the tail rotor power should be taken into

TABLE 2.2

TAIL ROTOR SIZING

HELICOPTER	ACTUAL TAIL ROTOR RADIUS [FT]	APPROXIMATION [FT]	
		[2.20]	[2.21]
AH-64	4.6	4.98	4.59
UH-1N	4.3	4.90	4.52
SH-3H	5.3	5.95	5.5
S-76	4.0	4.11	3.79
UH-60A	5.5	5.85	5.4
CH-53D	8.0	8.42	7.78
CH-53E	10.0	11.15	10.29

account, as well as all mechanical losses [transmission, etc.] for accurate calculations. However, a reasonable approximation can be obtained by considering only the main rotor and increasing this power figure by several percent to account for these losses.

Figure 2.2 is a plot of the induced, profile, parasite and total power curves for typical tail rotor helicopter.

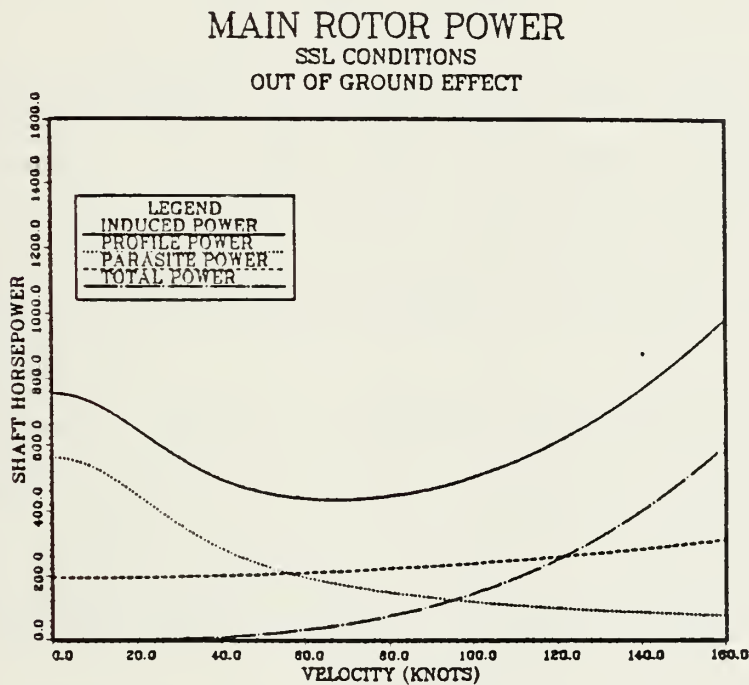


Figure 2.2. Power Required Versus Forward Velocity

The induced power drops off rapidly with increasing forward-velocity, whereas the parasite power increases rapidly.

Parasite power is the power required to overcome the drag forces created by the aircraft's geometry. These drag forces are due to pressure drag and skin friction.

Parasite drag is extremely sensitive to the helicopter's loading. It is generally a minimum for forward flight and increases for sideways flight. Helicopters are generally streamlined for forward flight and the flat plate area is a minimum in this direction. The equation for the parasite power is:

$$P_p = \frac{1}{2} \rho V_f^3 f_f \quad (2.21)$$

The parasite power is a function of the cube of the forward velocity. As such, with the advent of high speed helicopters a great deal of consideration has been placed on streamlining the geometric shape in order to reduce this power requirement.

Blade element theory is commonly used to develop the profile power equation for forward flight. An excellent development of this equation is given in Reference 1.

The profile power equation in forward flight is:

$$P_{of} = \frac{1}{8} \sigma C_{do} \rho A V_T^3 [1 + 4.3 \mu^2] \quad (2.22)$$

Equation (2.23) is a function primarily of the main rotor geometry. The variable with the most significance is the rotor tip velocity; increasing the tip velocity from 600 to 700 fps results in a 58.8 percent increase in profile power [assuming other factors are constant].

The induced power is a function of the induced velocity. In a hover, the total flow through the rotor system is induced. As the forward velocity increases, the mass flow rate through the rotor disc increases due to the forward translation of the helicopter. This reduces the induced velocity.

The equation for the induced power requirements at all forward velocities is:

$$P = T \cdot V_{it} \quad (2.23)$$

where

$$V_{it} = \left\{ -\frac{V_f^2/V^2}{2} + \sqrt{\left[V_f^2/2V^2\right]^2 + 1} \right\}^{1/2} \cdot V \quad (2.23a)$$

At high forward velocities, the induced power required can be approximated as:

$$P_i = W V_{it} = \frac{W^2}{2\rho A V_f} \quad (2.24)$$

The total power for forward flight is the sum of the induced, profile and parasite powers.

$$P_T = P_i + P_o + P_p \quad (2.25)$$

$$\begin{aligned}
 P_T = T \cdot V_{it} + \frac{1}{8} \sigma C_{do} \rho A V_T^3 [1 + 4.3 \mu^2] \\
 + \frac{1}{2} \rho f_f V_f^3
 \end{aligned}
 \tag{2.25a}$$

At high forward velocities, equation (2.23) can be substituted into equation (2.25), resulting in:

$$\begin{aligned}
 P_T = \frac{W^2}{2 \rho A V_f} + \frac{1}{8} \sigma C_{do} \rho A V_T^3 [1 + 4.3 \frac{V_f}{\Omega R}] \\
 + \frac{1}{2} \rho f_f V_f^3
 \end{aligned}
 \tag{2.26}$$

If one makes the following assumptions:

$$\begin{aligned}
 W &= \text{const} & C_{do} &= \text{const} \\
 \rho &= \text{const} & \sigma &= \text{const} \\
 V_T &= \text{const}
 \end{aligned}$$

Equation (2.26) reduces to

$$P_T = \frac{K_1}{R^2} + K_2 R^2 + P_p
 \tag{2.27}$$

The derivative of equation (2.27) with respect to radius is:

$$\frac{dP_T}{dR} = - \frac{2K_1}{R^3} + 2 K_2 R
 \tag{2.28}$$

Setting this equal to zero, one obtains:

$$- \frac{2K_1}{R^3} + 2 K_2 R = 0 \quad (2.28a)$$

$$\frac{R}{2} * [- \frac{2K_1}{R^3} + 2 K_2 R] = 0 \quad (2.28b)$$

$$\frac{K_1}{R^2} = K_2 R^2 \quad (2.28c)$$

$$P_i = P_o \quad (2.28d)$$

This defines point of minimum total power required for VMAX range. This corroborates with the results obtained by Waldo Carmona [Ref. 4].

If the total power required is differentiated with respect to forward velocity and is set equal to zero, it can be seen that

$$P_i = 3 P_o \quad (2.29)$$

or

$$\frac{W^2}{2\rho AV_f} = \frac{3\rho f V_f^2}{2} \quad (2.30)$$

Solving this equation for velocity results in:

$$V_f = \left[\left(\frac{W}{A} \frac{A}{3f_f} \right)^{1/2} \right]^{1/2} \text{ ft/sec} \quad (2.31)$$

According to Carmona [Ref. 4], this corresponds to the best endurance velocity.

K. DENSITY EFFECTS ON TOTAL POWER

The effect of density on the total power required in forward flight is as follows:

The general operating altitudes of a helicopter are below 10,000 feet. The corresponding ICAO STANDARD ATMOSPHERE range for density is

$$\rho = 0.0023769 \text{ [lb sec}^2\text{/ft}^4\text{]} \quad \text{SSL}$$

$$\rho = 0.0017553 \text{ [lb sec}^2\text{/ft}^4\text{]} \quad \text{at 10,000 feet}$$

ρ/ρ_{SSL} varies from 1 to .7385.

The effect on the components of P_T are as follows:
Induced Power:

$$1/\rho/\rho_{\text{SSL}} \Rightarrow 1 \text{ to } \frac{1}{.7385}$$

This translates to a 35 percent increase in the induced power.

Parasite and Profile Power:

Both parasite and profile powers are directly proportional to the density ratio. Therefore, as you go up in altitude both P_o and P_p are reduced.

III. CARPET PLOT DESIGN STUDY

A. DESCRIPTION OF PROBLEM

Preliminary helicopter design involves one with a wide range of choices. For any given payload and performance specifications, there are a number of helicopter designs that satisfy the requirements. The problem in the preliminary design process is narrowing these possibilities and selecting the design which will provide the best helicopter for the mission.

Obviously, the operating environmental constraints help to define the basic configuration. These constraints are usually specified in the Request for Proposal [RFP], in the case of a military helicopter. For example, typical constraints placed on the design of a Navy helicopter are the size of the ship deck and hangar from which it will be operating, the requirement for a blade fold system, dual engine configuration and IFR capability.

Even with these design constraints, there is still a great deal of leeway. In order to insure that the best helicopter design is selected, an appropriate number of solutions satisfying the specifications should be investigated. Since each solution is generally characterized by a different combination of design parameters, the

selection, according to Greenfield [Ref. 5], can best be made through a parametric study which allows for the optimization of many design parameters.

One method of parametric analysis used is Carpet Plots. This method is based on the simultaneous graphical solution of the weight and hover performance equations. To this solution set is added to the environmental constraints to the helicopters size. This effectively brackets the area of acceptable design solutions.

This method assumes that minimum gross weight is the criterion by which the best [or optimum] design parameters are selected.

B. ASSUMPTIONS

1. Airfoil used is a derivative of the NACA 0012 with the following mean approximate values from Reference 5.

a = slope of airfoil section lift curve, $dC_t/d\alpha$,
per rad.

$a = 5.73$

δ = blade section drag coefficient

$\delta_0 = .009$

$\delta_2 = .3$

2. a) The tail rotor radius is assumed to be .16 times the main rotor radius [Ref. 5].

b) The distance between the rotors, or tail rotor moment arm, λ_{TR} is $1.19R$ [Ref. 5]. These ratios reflect the values of maximum rotor diameter and overall length specified as size limitations.

3. $B = .97$. Historical approximation [Ref. 7].

C. METHODOLOGY

In order to properly develop the weight and performance equations required for a carpet plot design study, the payload and performance specifications of the helicopter are needed. This data is used to tailor the equations for the design.

The equations will be developed here for a four-place light helicopter. The equation development procedure is applicable to other size helicopters; the development for a medium helicopter, 20,000 lb weight class, is to be found in Appendix B.

The following specification requirements which are similar to those in Reference 5 will apply to this design:

1. The rotor diameter should be less than 35.2 feet.
2. The overall length should be less than 41.4 feet.
3. The gross weight of the helicopter should not exceed 2,450 lbs.
4. The helicopter should be capable of hovering, out of ground effect at 6,000 feet with an ambient air temperature of 95°F .

5. The useful load at hover shall consist of, as a minimum, 200 lbs for the pilot, 400 lbs of payload and sufficient fuel to give the helicopter up to three hours endurance at sea level conditions.

6. Maximum speed of at least 110 knots using Normal Rated Power, at sea level.

7. Total Power Required at 6,000 feet and 95°F shall be not more than 206.

D. HOVER EQUATIONS

1. The main rotor power required to hover out of ground effect is

Total Main Rotor Power [Hover] = Rotor Profile Power + Rotor Induced Power

$$P_T = \frac{1.13W}{550B\sqrt{2\rho_o}} \sqrt{\frac{DL}{\rho/\rho_o}} + \frac{6WV_T}{4400} \frac{\rho/\rho_o}{C_{LRO}} \left[\delta_0 + \delta_2 \left[\frac{C_{LRO}}{\alpha\rho/\rho_o} \right]^2 \right] \quad (3.1)$$

At an altitude of 6,000 feet and a temperature of 95° , $\rho/\rho_o = .749395$. Therefore, equation (1) can be simplified to:

$$P_{T6000/95^\circ F} = .035479W[DL]^{1/2} + \frac{.91971}{C_{LRO}} [10]^{-5} (1 + 1.80779 C_{LRO}^2) W V_T \quad (3.2)$$

The tail rotor thrust required to counterbalance the main rotor torque is:

$$T_{TR} = \frac{550 P_{TR}}{\ell_{TR} V_T} = \frac{550 P_T}{1.19 V_T} \quad (3.3)$$

where ℓ_{TR} has been defined as $1.19R$. With R_{TR} defined as $.16R$, the tail rotor disk loading can be written, using equation (3) as:

$$\begin{aligned} DL_{TR} &= \frac{T_{TR}}{A_{TR}} = \frac{550 P_T}{1.19 V_T} \frac{1}{\pi (.16R)^2} \\ &= \frac{550 P_T}{1.19 (.0256) V_T} \frac{DL}{W} \end{aligned} \quad (3.4)$$

Greenfield [Ref. 5], in his development, assumes that the tail rotor tip speed is equal to the main rotor tip speed and that $\delta_{TR} = .02$ and $\beta_{TR} = .90$. With these assumptions the equation for the tail rotor power required to hover can be written as:

$$\begin{aligned} P_{T_{TR_{Hover}}} &= 2055.7 \left[\frac{DL}{W \rho / \rho_0} \right]^{1/2} \left[\frac{P_{T_{Hover}}}{V_T} \right]^{3/2} \\ &+ \frac{.012605 P_{T_{Hover}}}{C_{LRTR}} \end{aligned} \quad (3.5)$$

The equation for the tail rotor mean blade lift coefficient can be written as

$$C_{LRTR} = \frac{P_T}{562.5(\rho/\rho_o)} \quad (3.6)$$

if it is assumed that the tail rotor is designed to counterbalance a sea level main rotor torque equivalent to 90 percent of the installed power.

Substituting equation (3.6) into equation (3.5) one obtains the following expression for hover tail rotor power:

$$P_{T_{TR6000/950}} = 2374.7 \left[\frac{DL}{W} \right]^{1/2} \left[\frac{P_{TH}}{V_T} \right]^{3/2} + 5.3134 \quad (3.7)$$

It is assumed that the gear losses amount to 3 percent and that there is a 1 percent cooling power loss, the total brake horsepower required to hover becomes:

$$P_T = \frac{P_{Tm} + P_{TTR}}{96} \quad (3.8)$$

Empirical studies have shown that the tail rotor power required to hover can be approximated by

$$P_{T_{AC}} \sim .8 \text{ [total horsepower to hover]}$$

This allows one to write the main rotor power required to hover as:

$$P_{Tm} = (.88)(P_{Tm}) \quad (3.9)$$

Following Greenfield's [Ref. 5] development further, if equations (3.2) and (3.7) are substituted in equation (3.8), one obtains

$$\begin{aligned}
 P_{T_{H6000/95^{\circ}}} &= .036757 W \sqrt{DL} \\
 &+ \frac{.95803}{C_{LRO}} (10)^{-5} [1 + 1.80779 C_{LRO}^2] W V_T \quad (3.10) \\
 &+ 2473.6 \sqrt{\frac{DL}{W}} \left[\frac{P_{Tm}}{V_T} \right]^{3/2} + 5.5348
 \end{aligned}$$

Utilizing the approximation for tail rotor power, equation (3.9), equation (3.10) can be solved for W (gross weight) as a function of variables V_T (tip speed), DL (rotor disk loading), C_{LRO} (rotor mean lift coefficient) and P_{T_H} (total power to hover).

$$W = \frac{K_1 \left[1 - 411.51 \frac{DL^{3/4}}{V_T^{3/2}} \left(1 + K_2 \frac{V_T}{\sqrt{DL}} \right)^{1/2} \right] - K_3}{V_T + K_4 \sqrt{DL}} \quad (3.11)$$

where:

$$K_1 = P_{T6000/90^{\circ}} \frac{(10)^5}{K_5} \quad (3.11a)$$

$$K_2 = \frac{.00025929}{C_{LRO}} (1 + 1.80779 C_{LRO}^2) \quad (3.11b)$$

$$K_3 = \frac{553480}{K_5} \quad (3.11c)$$

$$K_4 = \frac{3695.7}{K_5} \quad (3.11d)$$

$$K_5 = \frac{.95803}{C_{LRO}} (1 + 1.80779 C_{LRO}^2) \quad (3.11e)$$

Equation (3.11) has been programmed in Appendix B and solved for tip speeds from 600 to 700 cps and C_{LR} of .3 to .7.

Equation (3.11) is one of the two primary equations used to obtain the data required for a carpet plot design analysis. Generally, the variables V_T , DL , C_{LRO} and P_T , that are required for solution have specific ranges of values, depending on the weight class of the helicopter being designed. The graphical results of equation (3.11) for tip speeds of 600 to 700 fps and mean lift coefficients between .3 and .7 are illustrated in Figure 3.1.

Both the Fortran and Disspla programs, as well as a decision making flow chart are provided in Appendix C to aid in using this method for a design solution.

E. WEIGHT EQUATIONS

Weight equations need to be developed that realistically reflect the sizing class of the helicopter being designed. The evolution is greatly simplified if a specific engine

Weight Equation Plot: $CLR=0.5$

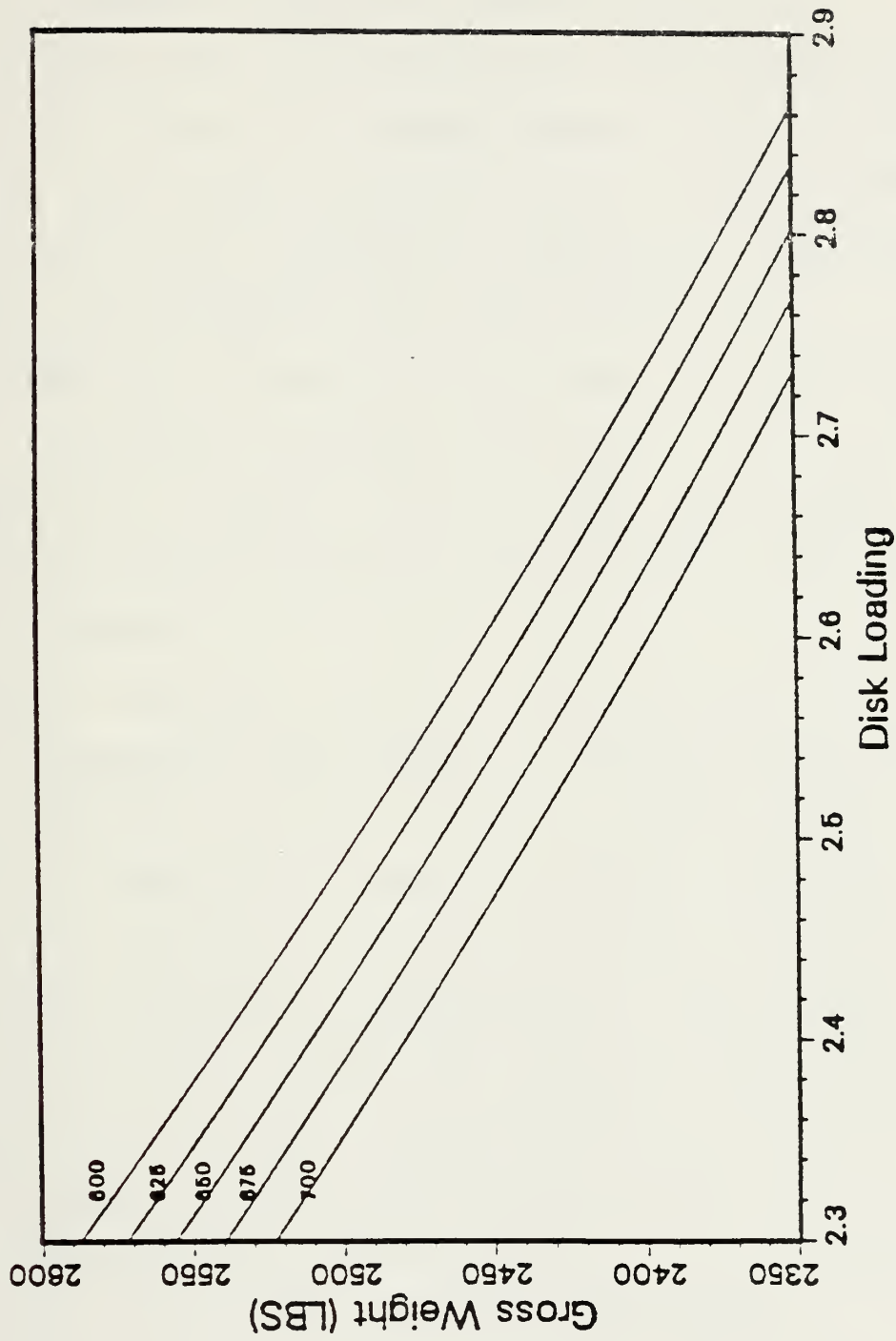


Figure 3.1. Weight Equation Plot: $C_{LR} = 0.5$

installation [# and horsepower] is assumed, since the weight of a number of components depend only on the installed power; this would include such terms as the engine controls and accessories. Another category would be those components whose weights depend on either the gross weight on two or more of the following in combination: rotor tip speed (V_T), rotor diameter (R), rotor solidity (σ).

The equations developed here are taken from the Hiller Aircraft Corporation Performance Data Report. [Ref. 5] In this report they assumed a specific engine installation, the Allison T-63 with a military power rating at sea level of 250 horsepower.

There is a possible problem of the validity of these weight relationships when applied to different helicopter design categories. However, assuming a specific engine determines a number of the component weights, and thus minimizes the inaccuracies. Using the weight estimation relationships developed in the Helicopter Design Manual [Ref. 2], the engine, control and accessory weight can be calculated and the weight formulas developed here applied to give a representative useful load and empty weight formula for preliminary design analysis. This is done in Appendix C, for a 20,000 pound class helicopter.

The following relations are used to reduce the component weight formulas for the specification helicopter:

$$W/DL = A = \pi R^2 \quad (3.12)$$

$$W/PL = MHP = 250 \quad (3.13)$$

(Military rating for Allison T-63 at sea level.) (PL = Power Loading.)

$$P = \sqrt{A}/V_T \quad (3.14)$$

Using these equations the component weight for the specified helicopter empty weight may be reduced to the following:

$$\text{Engine, Controls and Accessories} = 617.5 \text{ lbs.}$$

$$\text{Engine Section Group} \quad .053 [W/PL]^{1.07} = 19.5 \text{ lbs.} \quad (3.15)$$

$$\text{Main Trans- mission} \quad 10.43 \frac{W^{1.295}}{(PL V_T)^{.863}} = 1221 p^{.803} \quad (3.16)$$

$$\text{Rotor Drive Shaft} \quad 5.56 \frac{W^{1.05}}{(PL V_T)^{.7} (DL)^{.35}} = 266 p^{.7} \quad (3.17)$$

$$\text{Tail Rotor} \quad 32.22 \frac{W^{1.14}}{(PL V_T)^{1.7}} = \frac{17449}{V_T^{1.14}} \quad (3.18)$$

The engine, controls and accessories category includes such items as lubrication and oil cooling system, engines, communications, engine controls, engine accessories, instruments starting system, furnishing, flight controls, electrical system and stabilization. These are considered fixed weight items determined from specification of the engine and weight class of the helicopter.

$$\begin{array}{l} \text{Tail Rotor} \\ \text{Gear Box} \end{array} \quad 3.7 \frac{W^{.75}}{(PL V_T)^{.5} (DL)^{.25}} = 59.47 \sqrt{P} \quad (3.19)$$

$$\begin{array}{l} \text{Tail Rotor} \\ \text{Drive} \\ \text{Shaft} \end{array} \quad .124 \frac{W^{1.355}}{(PL V_T)^{.57} (DL)^{.785}} = 2.886 P^{.57} \sqrt{A} \quad (3.20)$$

$$\begin{array}{l} \text{Body and} \\ \text{Gear} \\ \text{Landing} \end{array} \quad = 1.91 W^{.916} + .0294 W^{.99}$$

$$\begin{array}{l} \text{Rotor} \\ \text{Blade} \\ \text{Teetering} \end{array} \quad 35.15 \frac{W^{1.185} \sigma^{.33}}{V_T (DL)^{.185}} = 35.15 \frac{W}{V_T} A^{.185} \sigma^{.33} \quad (3.21)$$

$$\begin{array}{l} \text{Rotor Blade} \\ \text{Artic-} \\ \text{ulated} \end{array} \quad 19.77 \frac{W^{1.205} \sigma^{.33}}{V_T (DL)^{.205}} = 19.77 \frac{W}{V_T} A^{.205} \sigma^{.33} \quad (3.22)$$

$$\begin{array}{l} \text{Rotor Hub} \\ \text{Teetering} \end{array} \quad .0088 \frac{W^{1.21}}{DL^{.21}} = .0088 W A^{.21} \quad (3.23)$$

$$\begin{array}{l} \text{Rotor Hub} \\ \text{Artic-} \\ \text{ulated} \end{array} \quad .00975 \frac{W^{1.21}}{DL^{.21}} = .00975 W A^{.21} \quad (3.24)$$

$$\text{Fuel System} \quad .416 \text{ per gallon capacity} = .0615 W_F \quad (3.25)$$

where W_F = fuel weight.

The individual component weights may now be combined into a single expression for the helicopter empty weight.

$$\begin{aligned} W_e = & 617.5 + .0617W_F = 1221P^{.863} + 266P^{.7} + \frac{17449}{V_T^{1.14}} \\ & + 58.47\sqrt{P} + 2.886P^{.57}\sqrt{A} + .191W^{.916} + .0294W^{.99} \\ & + \text{appropriate rotor blade and hub weights.} \end{aligned} \quad (3.26)$$

As stated earlier, the design specifications called for a useful load consisting of a pilot (200 lbs), payload (400 lbs) and the required fuel weight (W_F). The fuel weight is calculated for the Allison T-63 in the following manner: endurance of three hours at 85 percent of normal rated power for the T-63 is 180.2 HP and the specific fuel consumption at this power is .783 lbs fuel/BHP HR. Including an allowance for a three-minute warm-up at NRP and using a 5 percent correction factor on SFC, as specified in Reference 5, the fuel weight becomes:

$$W_F = 3(180.2)(.822) + \frac{3}{60} (212)(777) \quad (3.27)$$

An allowance should also be made for oil plus trapped fuel. This is estimated at 20 lbs.

The total useful load is the sum of the useful load items.

$$W_u = 200 + 400 + 452.6 + 20 = 1072.6 \text{ lbs} \quad (3.28)$$

A new variable, W_{BAR} , is defined as the sum of the empty weight plus useful load. It is the of equations (3.26) and (3.28).

$$W_{BAR} = 1717.9 + 1221P^{.863} = 266P^{.7} + \frac{17449}{V_T^{1.14}} + 58.47\sqrt{P} \\ + 2.886P^{.57}\sqrt{A} + .191W^{.916} + .0294W^{.99} \quad (3.29)$$

+ appropriate rotor blade and hub weights.

Equation (3.11) together with equation (3.29) form the basis of a carpet plot design study. These equations are solved simultaneously for W_{BAR} . This solution is best illustrated graphically, as in Figure 3.2. The graph in Figure 3.2 was generated for a specific value of C_{LR} over a range of tip speeds [600 to 700].

F. GRAPHICAL ANALYSIS

Graphs similar to Figure 3.1 are generated for several value of C_{LR} , and are then cross plotted to form Figure 3.2.

The mean lift coefficient, C_{LR} , values are selected based on what is considered the historical average range of

Helicopter Carpet Plots: $CLR=0.5$

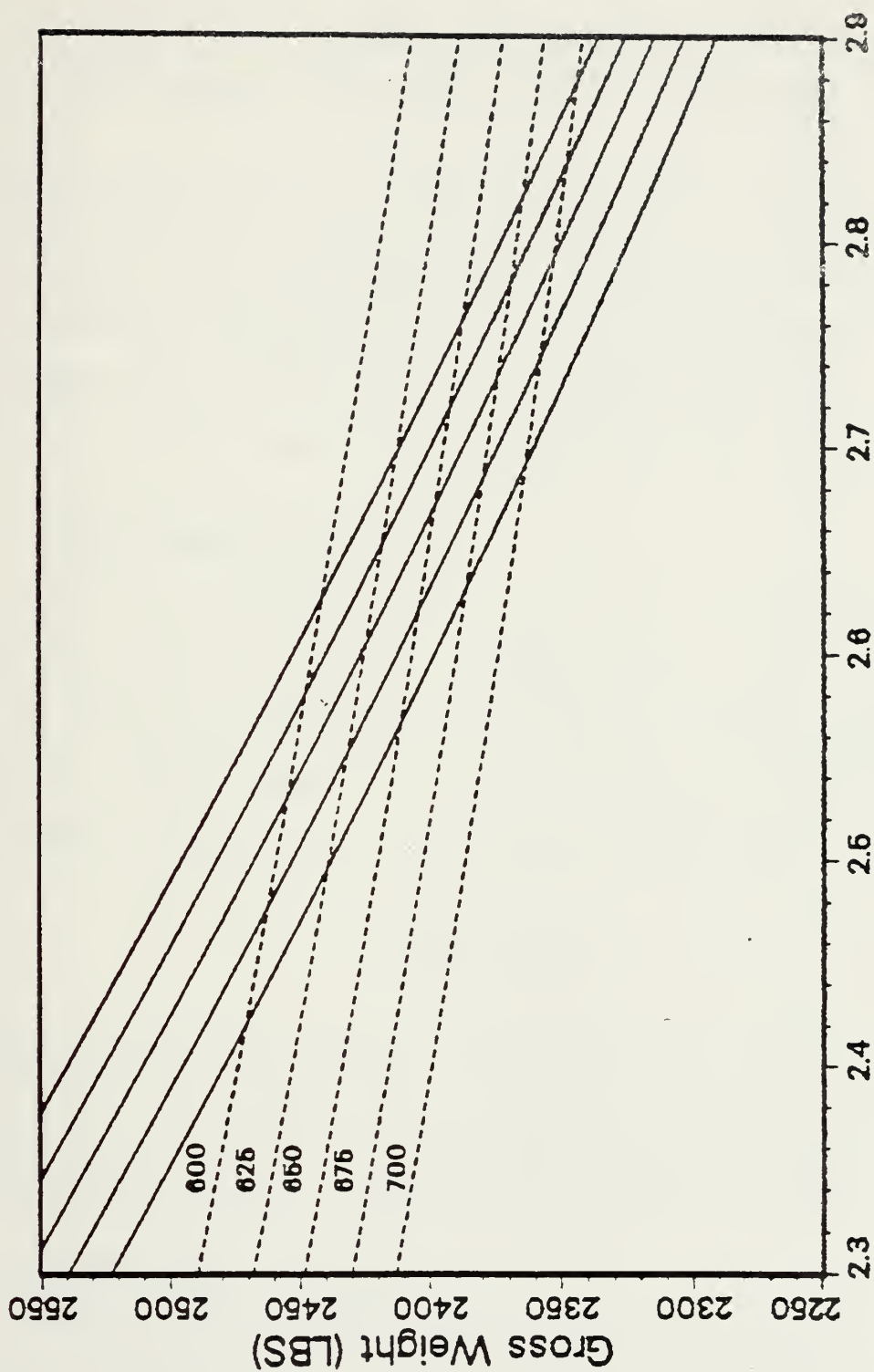


Figure 3.2. Helicopter Carpet Plots: $C_{LR} = 0.5$

values. Figure 3.3 is basic plot for a carpet plot design study. Programs are provided in Appendix D which will generate the required data sets and plots of Figures 3.2 and 3.3.

The solution field depicted in Figure 3.3 is too large to be of great analytic value and as such must be reduced. Three parameters, maximum gross weight, rotor diameter (both specified in the Design Specification) and the aspect ratio can be used to narrow the field of solutions.

1. Rotor Diameter Boundary

A net to exceed value for the rotor diameter is generally given in the design specifications. This limiting value is based on the operating environment of the helicopter. With R_{max} specified, there is a linear relationship between the disk loading and the gross weight.

$$DL = \frac{W}{A} = \frac{W}{\pi R^2}$$

The resulting bracketing of the solution field by applying both the maximum gross weight and maximum rotor diameter limits to the carpet plot are shown in Figure 3.4.

2. Respect Ratio Boundary

It is evident that a further restriction is still necessary to completely define the region of acceptable

Helicopter Carpet Plots

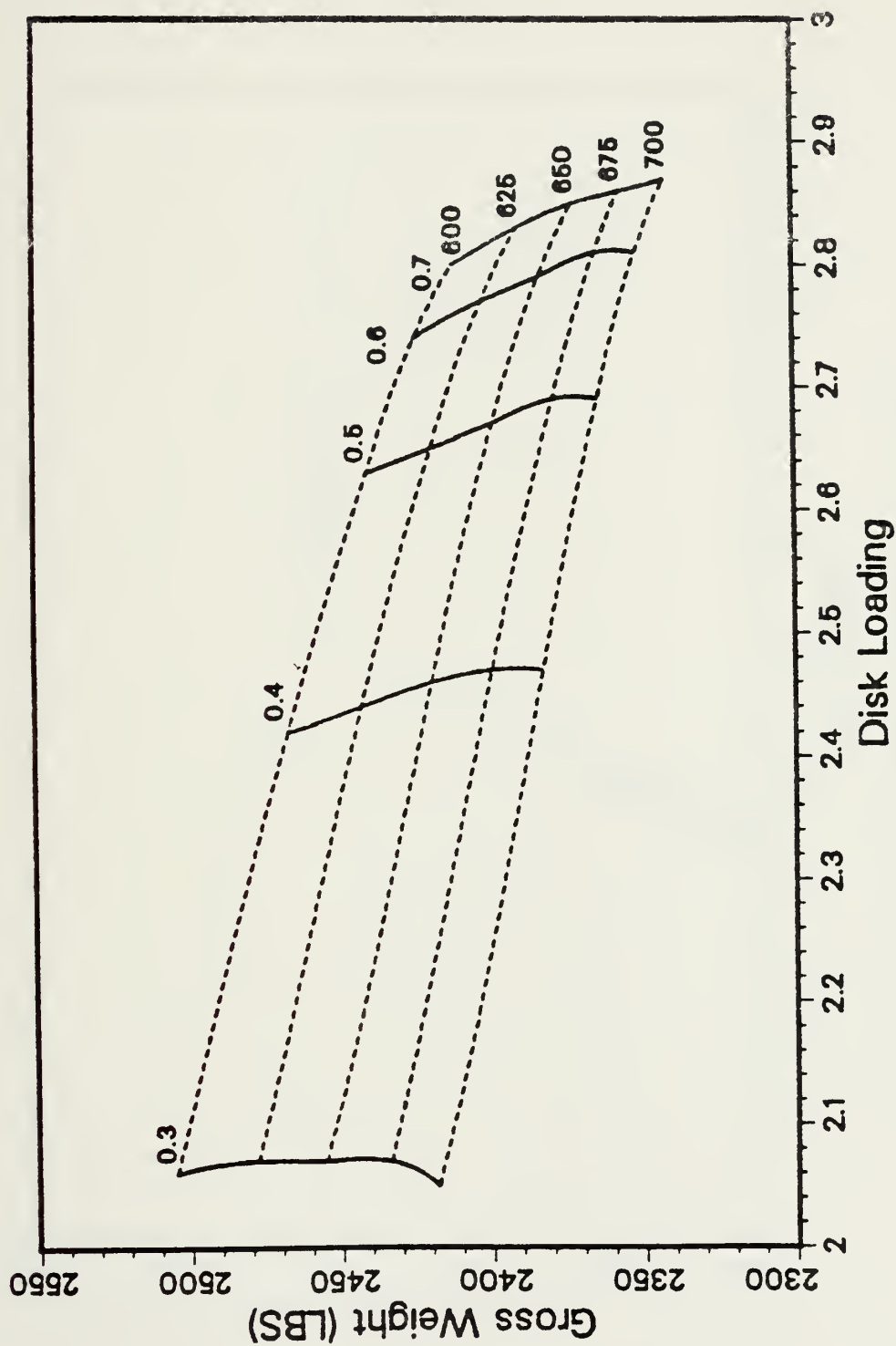


Figure 3.3. Helicopter Carpet Plots
Family of Solutions

Helicopter Carpet Plots

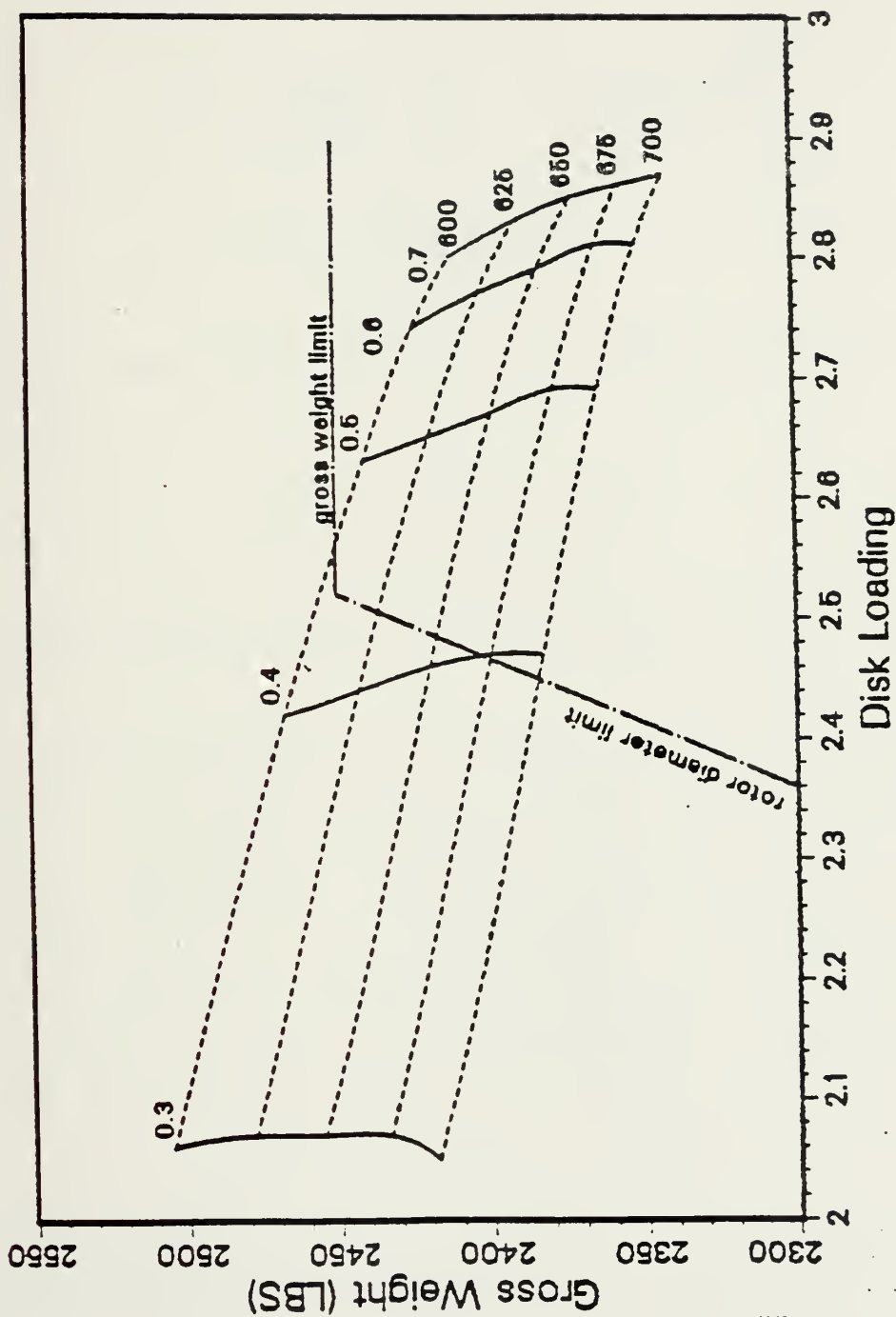


Figure 3.4. Helicopter Carpet Plots Rotor Diameter and Weight Limits

design solutions. Studies have indicated that a main rotor aspect ratio of 21,¹ is a representative upper limit. Thus

$$21 \geq \frac{R_{\langle mr \rangle}}{C_{\langle mr \rangle}} = \frac{b}{\pi \sigma} = \frac{b \rho_o C_{LR} V_T^2}{\sigma \pi DL}$$

or

$$DL \geq \frac{b \rho C_{LR} V_T^2}{126\pi}$$

For the case of a two bladed main rotor equation (3.30) reduces to:

$$DL \geq .000012 C_{LR} V_T^2$$

The determination of this boundary graphically is as follows:

The hover solution plot of Figure 3.2 is replotted² relative to the coordinates disk loading and design mean blade lift coefficient. The limiting curves for $DL = .000012 C_{LR} V_T^2$ are then plotted. The intersection with the appropriate constant tip speed lines of the hover solution represent the aspect ratio boundary; Figure 3.5.

¹For a helicopter rotor, the aspect ratio is defined as the radius divided by the chord.

²For clarity lines of constant gross weight are omitted.

aspect ratio boundary plot

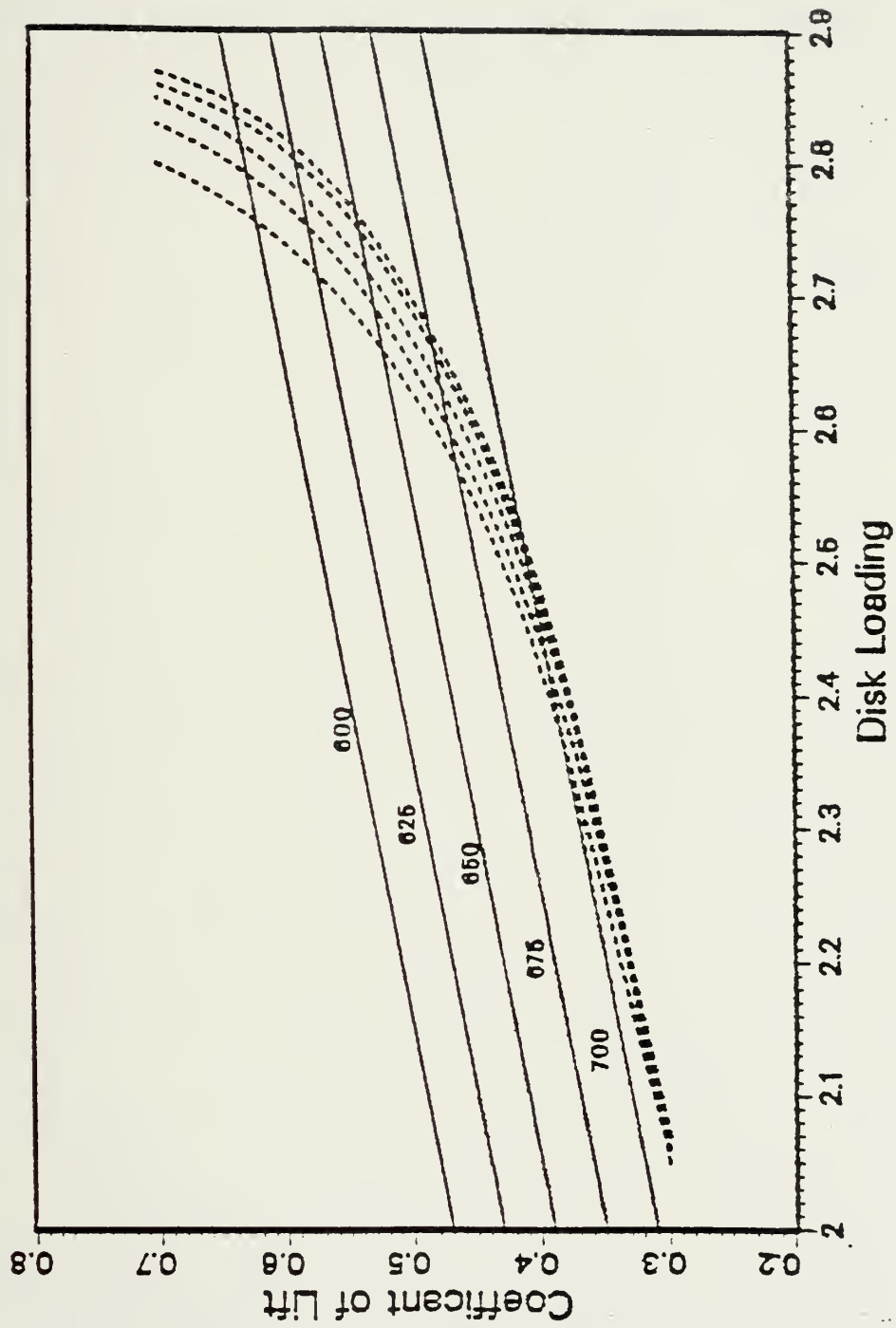


Figure 3.5. Aspect Ratio Boundary Plot

These intersection points are then cross plotted onto Figure 3.4. Figure 3.6 represents a graphical plot of the solution set satisfying the performance and structural design criteria of a small observation helicopter as specified in this study.

Helicopter Carpet Plots

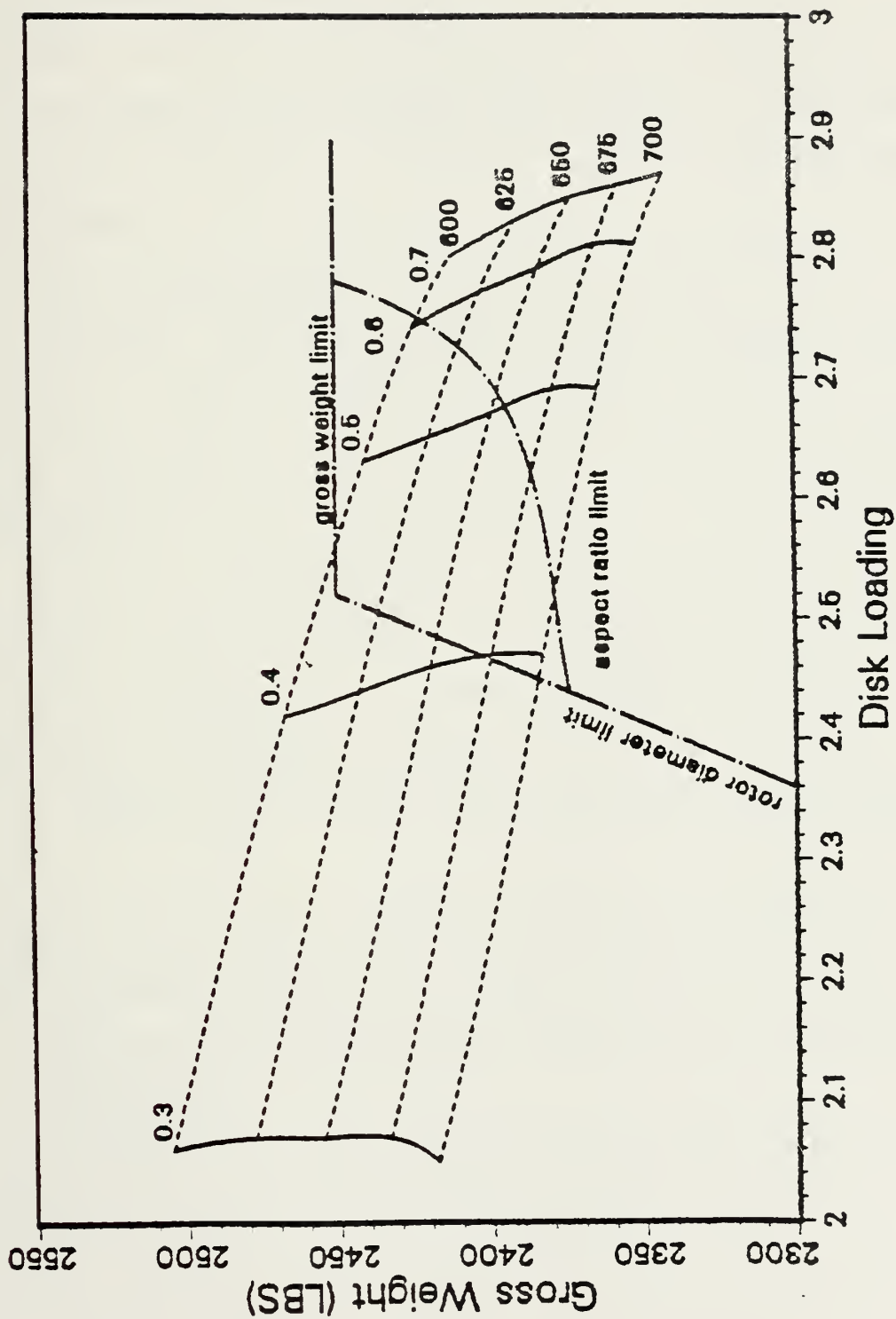


Figure 3.6. Helicopter Carpet Plots
Final Solution

IV. HESCOMP

A. DESCRIPTION OF PROGRAM.

HESCOMP is a helicopter sizing and performance computer program developed by the Boeing Vertol Company. The program was originally formulated to provide for rapid configuration design studies.

A number of programming options are available to the user of HESCOMP. When the type and mission profile of the helicopter are known, HESCOMP may be used to size the aircraft. Alternately, it may be used for mission profile calculations when the sizing details [gross weight, payload, engine size, etc.] are specified. A combination of these two options is also available; the program may be used to first size a helicopter for a primary mission and then calculate the off-design performance for other missions. Finally, HESCOMP may be used solely for obtaining helicopter weight.

Sensitivity studies involving both design and performance tradeoffs can easily be done with HESCOMP. Incremental multiplicative and additive factors can be imbedded in the input data.

The various helicopter configurations that may be studied using HESCOMP are detailed in Table 4.1.

TABLE 4.1

HELICOPTER CONFIGURATIONS WHICH MAY BE STUDIED USING HESCOMP

HELICOPTER CONFIGURATIONS WHICH MAY BE STUDIED USING HESCOMP.						
<div> <div>Additional Lift/Propulsion System Components Which Must be Added to "Pure" Conf.</div> <div>Helicopter Type (Both Single & Tandem Rotor)</div> </div>	Wing	Propeller for Auxiliary Propulsion	Auxiliary Independent Engines	Type of Auxiliary Independent Engines		
				T/Shaft	T/Fan	T/Jet
Pure Helicopter						
Winged Helicopter	X					
Compound Helicopter						
(1) Coupled (prim. engines drive auxiliary propulsion system)	X	X				
(2) Auxiliary independent propulsion system						
(a) T/Shaft engine	X	X	X	X		
(b) T/Fan engine	X		X		X	
(c) T/Jet engine	X		X			X
Auxiliary Propulsion Helicopter						
(1) Coupled (prim. engines drive auxiliary propulsion system)		X				
(2) Auxiliary independent propulsion system						
(a) T/Shaft engine		X	X	X		
(b) T/Fan engine			X		X	
(c) T/Jet engine			X			X
Coaxial Rotor Helicopter						
(1) Coupled (prim. engines drive auxiliary propulsion system)		X				
(2) Auxiliary independent propulsion system						
(a) T/Shaft engine		X	X	X		
(b) T/Fan engine			X		X	
(c) T/Jet engine			X			X

B. PROGRAM MODIFICATIONS AND IMPLEMENTATION

The computer program received from Boeing Vertol required some modification and reformatting in order to run properly on the Naval Postgraduate School IBM system. These alterations did not, however, alter the program output or usability.

HESCOMP, as received from Boeing Vertol, was 17821 lines long and set-up as a sequential data set to be assemble on a 'G compiler'. The Batch processing system at the Naval Postgraduate School accepts only programs set to run on 'H compiler'. Normally, the differences between these two compilers are minor and programs that run on one will run on the other. However, this was not the case with HESCOMP.

In order to facilitate the program debugging process, HESCOMP was reformatted as a partitioned data set. What this effectively did was to break the program down into eight members of approximately 2000 lines. The program breakdown is illustrated in Table 4.2.

Each of these were compiled individually and then error codes analyzed. The member data set was then modified as required to properly compile.

Once all the members of the partitioned data set compiled properly, HESCOMP was again formatted as a sequential data set and run utilizing input data for

which there was a known output. This insured that the modifications made to the original program had not altered the logic, ie., gave faulty results.

The control language program to access HESCOMB on the Batch processing system and a sample input and out data set are shown in Appendix D. These are also available on the Aero disk for copying and use.

TABLE 4.2

PARTITIONED DATA SET

MEMBER NAME	LINE NUMBER	SIZE	FIRST ROUTINE
S1	1 - 1681	1681	AERO
S2	1682 - 4132	2451	CLIMB
S3	4133 - 6531	2399	XIBIV
S4	6532 - 8974	2443	POWAVL
S5	8975 - 10870	1896	PRINT 1
S6	10871 - 13042	2172	ROT POW
S7	13043 - 15383	2341	CRUS 3
S8	15384 - 17821	2448	TAXI

C. PROGRAM FLOW

The program is conceptually outlined in Figure 4.1, [Ref. 7]. The program flow is monitored by a general loop, which controls a series of peripheral programs. There are

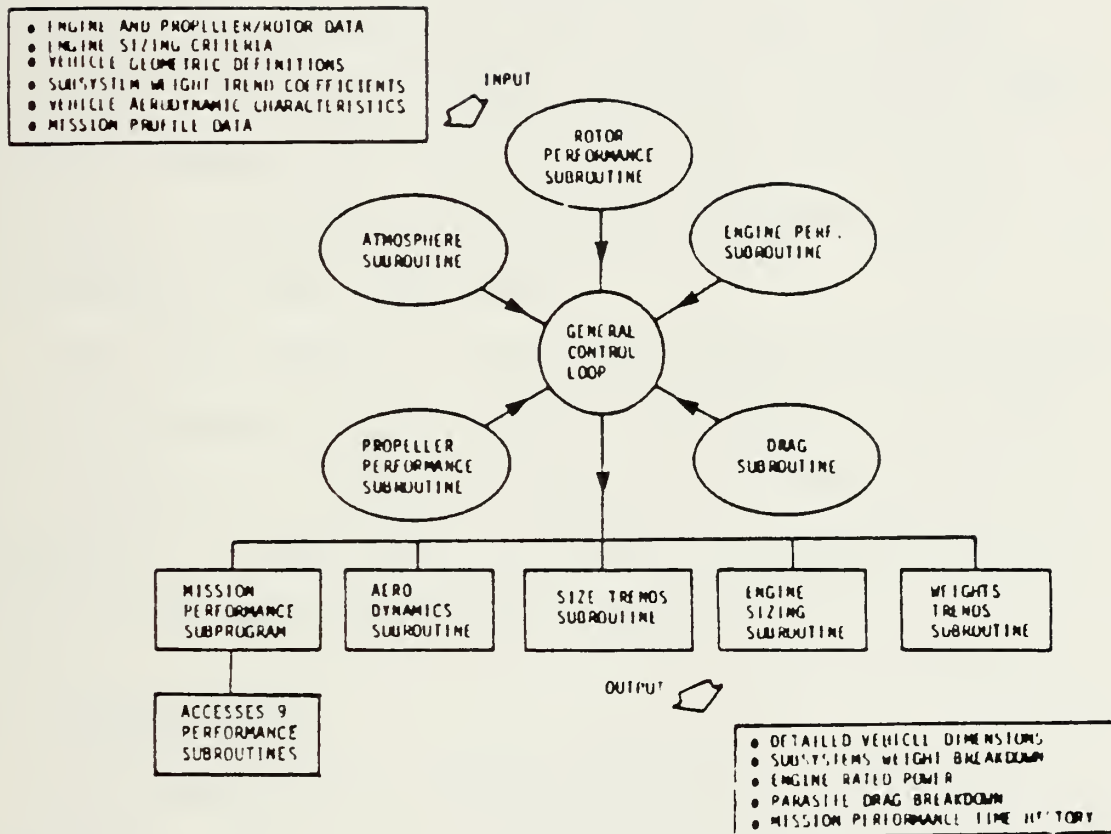


Figure 4.1. HESCOMP Program Flow

a total of 44 subroutines. Detailed program descriptions can be found in Section 4 of the HESCOMP User's Manual.

D. PROGRAM INPUT

Program input can be loosely group into ten categories: general information, aircraft descriptive information, mission profile information, rotor tip speed schedule, incremental rotor performance, auxiliary propulsion input schedule, engine cycle information, rotor performance information, propeller performance information, and supplementary input information.

The actual amount of input data requires varies greatly with the program options selected. An example of a data set formatted to run on the IBM system is shown in Appendix E. A more detailed explantion is available in Section 5 of the HESCOMP User's Manual.

E. PROGRAM OUTPUT

An example of the program output is included in Appendix E. The printout consists of general data, input data, sizing data [program output] and mission performance data [for the size helicopter]. Detailed descriptions of these and diagnostic error statements are described in Section 6 of Reference 6.

V. CONCLUSIONS AND RECOMMENDATIONS

Three approaches to analyzing a preliminary helicopter design were explored in the course of this paper. It was found that a number of the performance equations could be greatly simplified with little degradation in the final results. A sensitivity analysis brought further insight into the inter-play of the parameters and how changes in them tended to effect the helicopter performance equations.

Carpet Plots provided the most interesting method of analysis. Development of a graphical solution matrix using this method provides a usual interpretation of what is occurring when key parameters are varied.

Two cases were explored; a light observation helicopter in the 3,000 pound weight class and a heavier utility helicopter in the 20,000 pound weight class. The Carpet Plot method provided reasonable solutions in both cases. In doing the analysis for the utility helicopter, the initial weight estimation equation had to be adjusted upward by approximately 2,000 pounds for the equations to intersect properly. This is not considered a limitation to this method of analysis, however, it does point up an area for further investigation. It may be possible to develop more accurate weighing factors for this equation when dealing with higher gross weight helicopters.

HESCOMP provides a plethora of information to the user. However, the price is the amount of inputted data required for even a simplified analysis. At a preliminary design level of analysis, the other methods explored provide a quicker first-cut look at the potential design.

APPENDIX A: NOMENCLATURE

TERM	DEFINITION	UNITS
a	Slope of Airfoil Section Lift Curve	Radians
A	Rotor Disk Area	ft ²
AR	Aspect Ratio	Dimensionless
A _{TR}	Tail Rotor Disk Area	ft ²
b	Number of Rotor Baldes	Dimensionless
B	Tip Loss Factor	Dimensionless
C	Main Rotor Cord	ft
C _{do}	Profile Drag Coefficient at Zero Lift	Dimensionless
C _{LRO}	Design Mean Blade Lift Coefficient at Sea Level	Dimensionless
C _T	Coefficient of Thrust	Dimensionless
C _p	Coefficient of Power	Dimensionless
δ	Blade Section Drag Coefficient	Dimensionless
DL	Disk Loading	lb/ft ²
FM	Figure of Merit	Dimensionless
HP	Horsepower	
L _{TR}	Tail Rotor Moment Arm	ft
ρ	Air Density	lb sec ² /ft ⁴
μ	Advance Ratio	Dimensionless
R	Rotor Radius	ft

TERM	DEFINITION	UNITS
P_T	Total Power	HP
P_{TM}	Main Rotor Total Power	HP
P_{TTR}	Tail Rotor Total Power	Hp
P_O	Profile Power	HP
P_i	Induced Power	HP
P_p	Parasite Power	HP
PL	Power Loading	LB/HP
R	Rotor Radius	ft
T	Thrust	HP
V_I	Induced Velocity	ft/sec
V_F	Forward Velocity	ft/sec
V	Aircraft Forward Speed	ft/sec
V_T	Rotor Tip Speed	ft/sec
W	Aircraft Gross Weight	lbs
W_C	Empty Weight	lbs
W_F	Fuel Weight	lbs
W_u	Useful Load	lbs
W_{BAR}	Empty Weight Plust Useful Load	lbs
σ	Solidity	Dimensionless

APPENDIX B: CARPET PLOT FORMULATION FOR 20,000 LB.
CLASS HELICOPTER

B1 SPECIFICATIONS:

Maximum Gross Weight: 20,000 pounds
Maximum Rotor Diameter: 30 feet

B2 PRELIMINARY ENGINE SIZING:

B2.1 Utilize equation (2.14) to determine engine horsepower category.

$$W = [4.753P_T R]^{2/3}$$

$$20,000 = [47.53P_T 30]^{2/3}$$

$$P_T = 1983 \text{ HP}$$

B2.2 Use the engine selection parameters tables B.1 to determine the number and type of power plant [table taken from Reference 3].

B2.2a Type and number selected: 2 type C.

B2.2b Specifications:

Dry Weight Per Engine: 423 pounds

Shaft Horsepower at Standard Sea Level:

Military 1561 HP

Normal 1318 HP

B3 WEIGHT EQUATION FORMULATION

B3.1 To obtain the engine control and accessory weight use items 7, 9, 10, 11, 12 and 13 of the weight estimation relationships developed in Reference 3 for a utility helicopter:
#7: 609 lbs; #9: 129 lbs; #10: 76 lbs;
#11: 410 lbs; #12: 439 lbs; and #13: 302 lbs.

TABLE B.1

ENGINE SELECTION PARAMETERS

The following turboshaft power plant data are presented for one engine.

Engines:	A	B	C	D*	E	F
Dry Weight (lbs)	158	288	423	709	580	750
SHP (ssl) Military	420	708	1561	1800	2500	3400
Normal	370	659	1318	1530	2200	3000
Cruise	278	494	1989	1148	1650	2250
SFC (ssl) Military	.650	.573	.460	.595	.615	.543
Normal	.651	.573	.470	.606	.622	.562
Cruise	.709	.599	.510	.661	.678	.610
Initial Costs	\$93K	\$100K	\$580K	\$360K	\$640K	\$700K
Operating Cost per hour/engine	\$8	\$16	\$20	\$35	\$40	\$60
Preventative Maint per hour/engine	\$25	\$50	\$100	\$125	\$160	\$220
MTBMA (hrs)	3.5	3.0	2.0	3.0	4.0	3.5
MDT (hrs)	0.7	0.6	0.5	1.3	2.0	2.6
MTBF (hrs)	185	210	205	285	280	320
MTBR (hrs)	600	750	800	800	1000	750

B3.2 Simplifications

$$\frac{W}{DL} - A = \pi R^2, \quad \frac{W}{\ell_{pm}} = \text{MHP} = 31,00; \quad P = \sqrt{\frac{A}{V_T}}$$

B3.3 Engine Group

$$.053(5100)^{1.07} = 272 \text{ lbs}$$

B3.4 Main Transmission

$$\begin{aligned} 10.43 \frac{W^{1.295}}{(\ell_{pm} V_t)^{.863} \left[\frac{W}{A}\right]^{.432}} &= 10.43 \frac{W^{.863} A^{+.432}}{(\ell_{pm})^{.863} V_T^{.863}} \\ &= (10.43)(3100)^{.863} P^{.863} \\ &= 10,748 P^{.863} \end{aligned}$$

B3.5 Rotor Drive Shaft

$$\begin{aligned} 5.56 \frac{W^{1.05}}{(\ell_{pm} V_T)^{.7} \left[\frac{W}{A}\right]^{.35}} &= 5.56(3100)^{.7} P^{.7} \\ &= 1545 P^{.7} \end{aligned}$$

B3.6 Tail Rotor

$$32.22 \frac{W^{1.14}}{(\ell_{pm} V_T)^{1.14}} = \frac{307,600}{V_T^{1.14}}$$

B3.7 Tail Rotor Gear Box

$$3.7 \frac{W^{.75}}{(\ell \text{pm } V_T)^{.5} \left[\frac{W}{A} \right]^{.25}} = (3.7)(3100)^{.5} P^{.5}$$

$$= 206 P^{.5}$$

B3.8 Tail Rotor Drive Shaft

$$.124 \frac{W^{1.355}}{(\ell \text{pm})^{.57} \frac{W^{.785}}{A^{.785}}} = (.124)(3100)^{.57} P^{.57} \sqrt{A}$$

$$= 12.12 P^{.57} \sqrt{A}$$

B3.9 Landing Gear

$$= .191 W^{.916} + .0294 W^{.99}$$

B3.10 Rotor Blades Articulated

$$19.77 \frac{W^{1.206} \sigma^{.33}}{V_T \text{ DL}^{.205}}$$

$$= 19.77 \frac{W}{V_T} A^{.205} \sigma^{.33}$$

B3.11 Rotor Hub Articulated

$$.00975 \frac{W^{1.21}}{\text{DL}^{.21}} = .00975 W A^{.21}$$

B3.12 Fuel System .0615 W_F

Calculation of fuel weight three hours at
cruise SHP

1513 lbs + 10%

1664 lbs

B3.13 Total Equation

$$WB = 12,987,* + 107948P^{.863} + 1545P^{.7}$$

$$+ \frac{307600}{V_T^{1.14}} + 206P^{.5} + 12.12P^{.57} \sqrt{A}$$

$$+ .191W^{.916} + .0294W^{.99}$$

$$+ 19.77 \frac{W}{V_T} A^{.205} S^{.33} + .00975WA^{.21}$$

B4 HOVER EQUATION

Following the formulation in Section of Chapter 3,
the weight equation based on the design mean lift coefficient and power required is:

$$W = \frac{K_2 \left[1 - 411.51 \frac{DL^{3/4}}{V_T^{3/2}} \left(1 + K_3 \frac{V_T}{\sqrt{DL}} \right)^{1/2} \right] - K_4}{V_T + K_5 \sqrt{DL}}$$

*This number was increased from 8987 to 12987 to bring the curves together. This reflects a 4000 lb useful load.

where:

$$K_1 = \frac{.9583}{C_{LRO}} (1 + 1.8078 C_{LRO}^2)$$

$$K_2 = P_{T6000}/950 \frac{(10^5)}{K_1}$$

$$K_3 = \frac{0.00025929}{C_{LRO}} (1 + 1.8078 C_{LRO}^2)$$

$$K_4 = \frac{553480.0}{K_1}$$

$$K_5 = \frac{3695.7}{K_1}$$

B.5 GRAPHICAL RESULTS

Figure B.1 is an example of equation (3.13) plotted against equation (B.4) for a specific design mean lift coefficient.

Figure B.2 illustrates the family of curves obtained when the design mean lift coefficient is varied from 0.3 to 0.7 .

In Figure B.3 the solution matrix depicted in Figure B.2 is narrowed by the constraints placed on the gross weight, rotor diameter and aspect ratio.

Helicopter Carpet Plots: $CLR=.70$ Utility Class

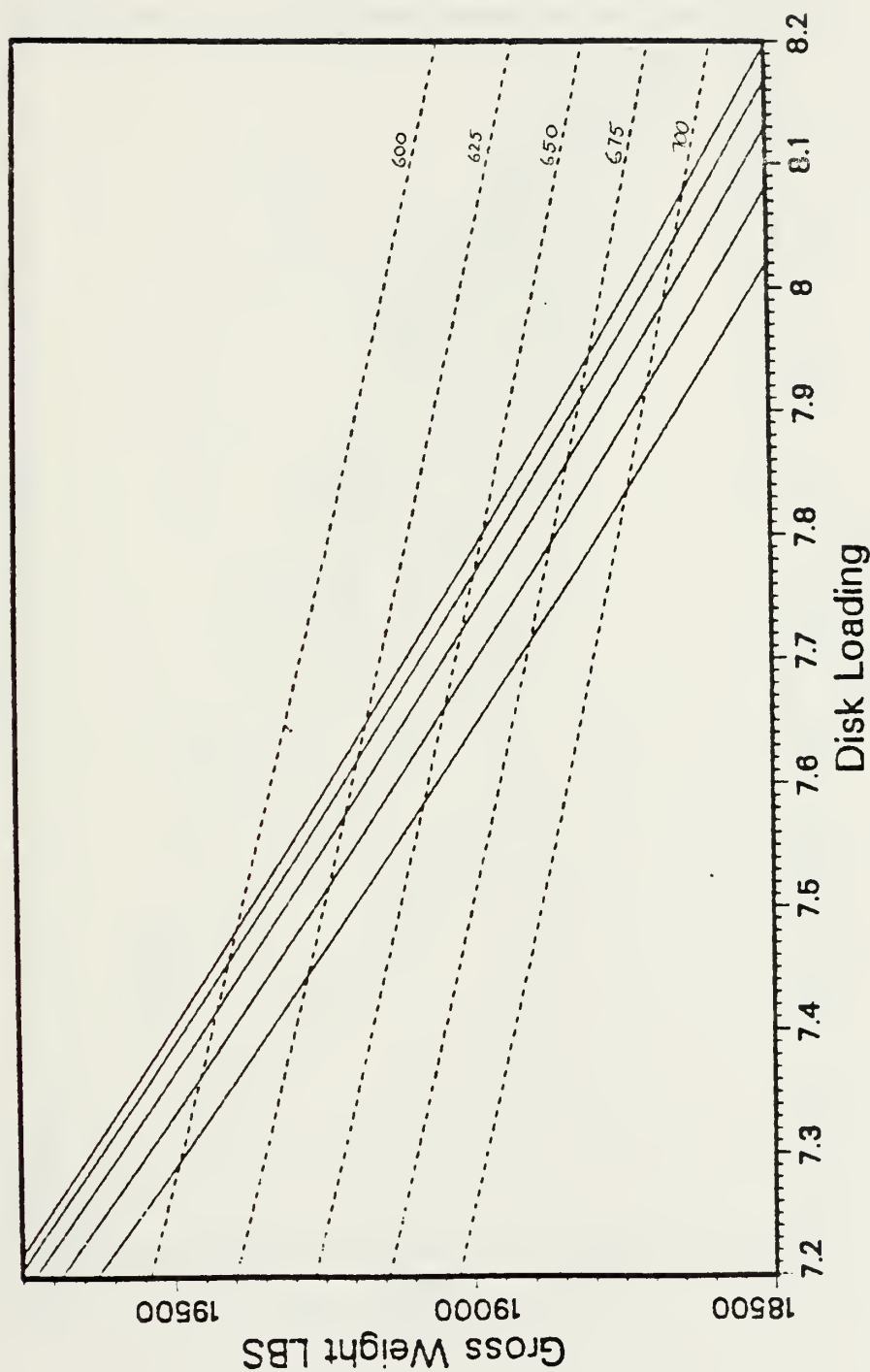


Figure B1. Helicopter Carpet Plots: $CLR = .70$
Utility Class

Helicopter Carpet Plots Utility Class

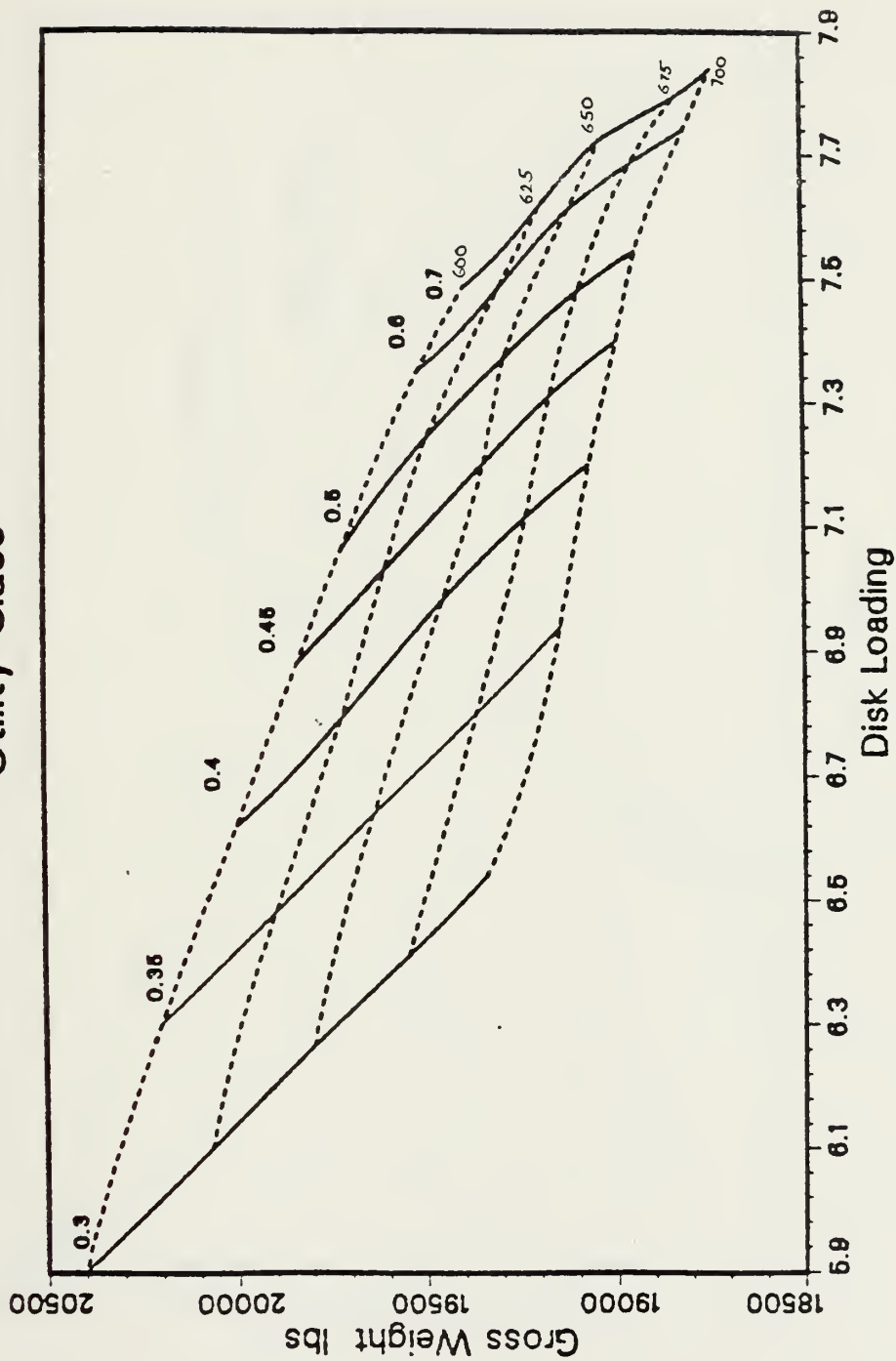


Figure B2. Helicopter Carpet Plots
Utility Class

Helicopter Carpet Plots Utility Class

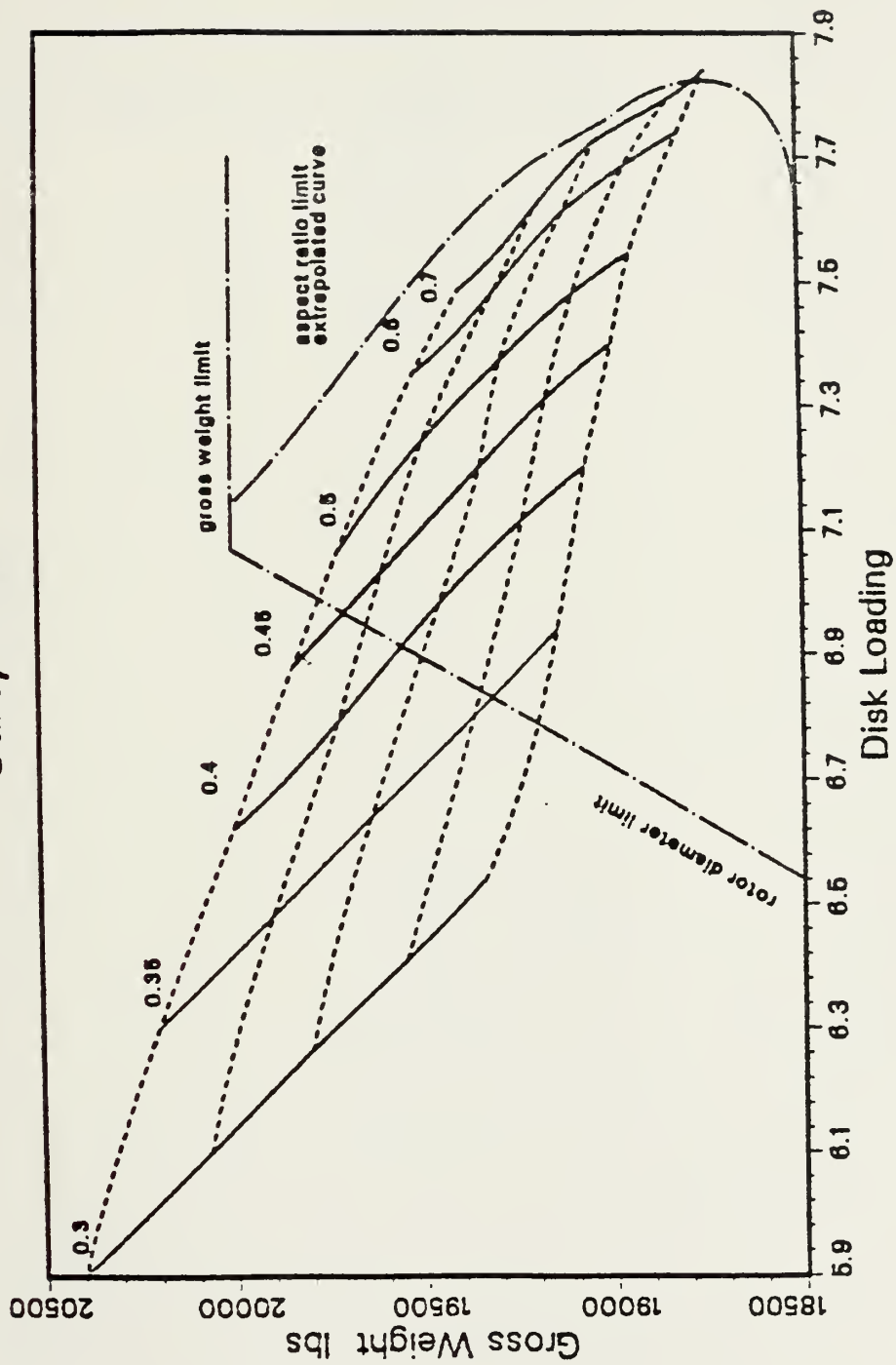
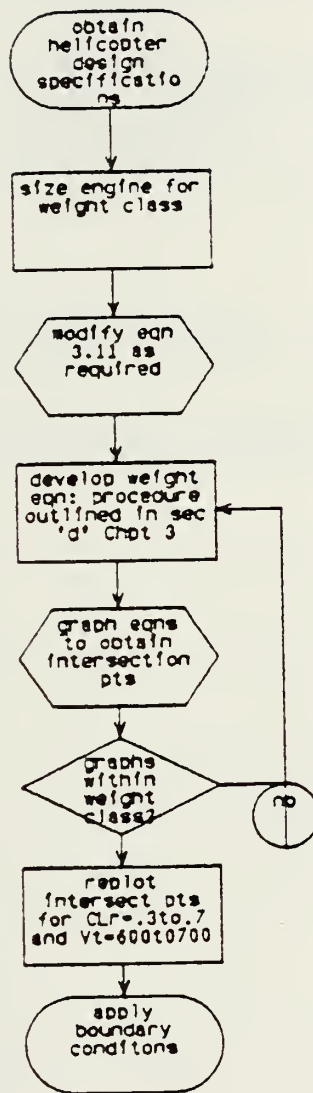


Figure B3. Helicopter Carpet Plots
Utility Class

APPENDIX C. CARPET PLOT METHODOLOGY FLOW CHART AND EXAMPLE PROGRAMS:

This section contains a flow chart to help organize a carpet analysis and example IBM computer programs to produce the data sets and display graphs.




```

CALL HEIGET (-20)
CALL GRAF (2.3,1,2.9,2250.,50.,2550.,
1,GRID=5)
CALL THKCEV (-C18)
CALL LEGLIN
CALL CURVE (DI,W1,95,0)
CALL CURVE (DI,W2,95,0)
CALL CURVE (DI,W3,95,0)
CALL CURVE (DI,W4,95,0)
CALL CURVE (DI,W5,95,0)
CALL DASE
CALL CURVE (DI,WE1,95,0)
CALL CURVE (DI,WE2,95,0)
CALL CURVE (DI,WE3,95,0)
CALL CURVE (DI,WE4,95,0)
CALL CURVE (DI,WE5,95,0)
CALL THKCEV (-C30)
C CALL BLREC (4.2,4.65,1.6,1.35,1)
C CALL GRID (1,1YGRID)
C CALL BLOFF (1)
MAXLIN=LINEST (IPAK1,300,20)
CALL HEIGHT (-12)
CALL LINESP (2.0)
C CALL LINES ('(E) EIGHTS',IPAK1,1)
C CALL LINES ('(I) INUCEDT',IPAK1,2)
C CALL LINES ('(F) FCFIIES',IPAK1,3)
C CALL LINES ('(F) ABASITES',IPAK1,4)
C CALL MYLEGN ('(F) CWEEF (C) CURVES',10)
C CALL LEGEND (IPAK1,4,4.43,4.8)
CALL DONEFL
STOP
C FORMAT STATEMENTS
70 FORMAT (5(2X,F10.3))
71 FORMAT (6(2X,F10.3))
END

```



```

C---- CALL DISSELA ROUTINES FOR PLOT -----
C
CALL TEK618
CALL MEDEUF
CALL RESET (3HALL)
CALL HASCAL ('SCREEN')
CALL PAGE (12.0, 9.5)
CALL OFACE (0.0)
CALL PHYSCR (1.0, 1.2)
CALL AREA2D (10.0, 6.5)
CALL FRAME
CALL SWISSL
CALL BASALF ('L/CSTD')
CALL MIXALF ('STAND')
CALL INTAXS
CALL YTICKS (5)
CALL XTICKS (5)
CALL SHDCHR (.90, 1., .015, 1)
CALL HEIGHT (.16)
CALL XNAME ('(C)ISK (L) OADING$', 100)
CALL YNAME ('(G)RCSS (W) EIGHT' (LBS) )$', 100)
CALL HEIGHT (.290)
CALL HEADIN ('(H)ELICOPTER (C)ARPET (P) LOT$',
1 100, 1.0, 1)
CALL HEIGHT (.20)
CALL GRAF (2.0, .1, 3.0, 2300., 50., 2550.)
IYGRID=5
CALL THKCBV (.018)
CALL PABA3
CALL LEGLIN
CALL CURVE (DL3, W3, 5, 0)
CALL CURVE (DL4, W4, 5, 0)
CALL CURVE (DL5, W5, 5, 0)
CALL CURVE (DL6, W6, 5, 0)
CALL CURVE (DL7, W7, 5, 0)
CALL DASE
CALL CURVE (DVT1, WVT1, 5, 0)
CALL CURVE (DVT2, WVT2, 5, 0)
CALL CURVE (DVT3, WVT3, 5, 0)
CALL CURVE (DVT4, WVT4, 5, 0)
CALL CURVE (DVT5, WVT5, 5, 0)
CALL THKCBV (.030)
CALL BLREC (4.2, 4.65, 1.6, 1.35, 1)
C CALL GRIL (1, IYGRID)
C CALL BLOFF (1)
C MAXLIN=LINEST (IPAK1, 300, 20)
C CALL HEIGHT (.12)
C CALL LINESP (2.0)
C CALL LINES ('(W) EIGHT$', IPAK1, 1)
C CALL LINES ('(I) NUICED$', IPAK1, 2)
C CALL LINES ('(F) RCFILES$', IPAK1, 3)
C CALL LINES ('(F) ARASITE$', IPAK1, 4)
C CALL MYLEGN ('(F) CREF (C) URVES', 16)
C CALL LEGEND (IPAK1, 4, 4.43, 4.8)
C CALL DONEEL
STOP
C FCBMAT STATEMENTS
C70 FCBMAT (5 (2X, F10.3))
C71 FCBMAT (6 (2X, F10.3))
END

```



```

1      100.3.25,7.55)
CALL NEIGH1 (-20)
CALL GRAF (2.0,.1,2.9,.2,.05,.8)
IYGRID=5
CALL THKCEV (.C18)
CALL PARA3
CALL LEGLIN
CALL CURVE (DI,C600,10,0)
CALL CURVE (DI,C625,10,0)
CALL CURVE (DI,C650,10,0)
CALL CURVE (DI,C675,10,0)
CALL CURVE (DI,C700,10,0)
CALL DASH
CALL CURVE (DVT1,C1R,5,0)
CALL CURVE (DVT2,C1R,5,0)
CALL CURVE (DVT3,C1R,5,0)
CALL CURVE (DVT4,C1R,5,0)
CALL CURVE (DVT5,C1R,5,0)
CALL THKCEV (.C30)
CALL DONEEL
STOP
END

```


DATA D1/2-52,2.9/
 DATA WMG/2450.,2450./
 DATA D2/2-36,2.52/
 DATA RDB/2300.,2450./

C
C
C

----- CALL DISSELA ROUTINES FOR PLOT -----

CALL TEK618
 CALL MEDEUF
 CALL RESIST (3HAIL)
 CALL HWSICAL ('SCREEN')
 CALL PAGE (12.C, 9.5)
 CALL GRACE (0.0)
 CALL PHYSSCR (1.0, 1.2)
 CALL AFEA2D (10., 6.5)
 CALL FRAME
 CALL SWISSL
 CALL BASALF ('I/CSTF')
 CALL MIXALF ('STAND')
 CALL INTAXS
 CALL YTICKS (5)
 CALL XTICKS (5)
 CALL SHDCHR (-90, 1., .015, 1)
 CALL HEIGHT (-.16)
 CALL XNAME ('(L)ISK (L)LOADING:', 100)
 CALL YNAME ('(G)RCSS (W)EIGHT (LBS)', 5', 100)
 CALL HEIGHT (-.290)
 CALL HEACIN ('(H)ELICOPTER (C)PRPET (P)LOTSS',
 100, 1.0, 1)
 CALL HEIGHT (-.20)
 CALL GRAF (2.C, -1, 3.C, 230C., 5C., 2550.)
 IYGRID=5
 CALL THKCBV (.C18)
 CALL PARAB
 CALL LEGLIN
 CALL CURVE (D13, W3, 5, 0)
 CALL CURVE (D14, W4, 5, 0)
 CALL CURVE (D15, W5, 5, 0)
 CALL CURVE (D16, W6, 5, 0)
 CALL CURVE (D17, W7, 5, 0)
 CALL DASE
 CALL CURVE (DVT1, WVT1, 5, 0)
 CALL CURVE (DVT2, WVT2, 5, 0)
 CALL CURVE (DVT3, WVT3, 5, 0)
 CALL CURVE (DVT4, WVT4, 5, 0)
 CALL CURVE (DVT5, WVT5, 5, 0)
 CALL THKCBV (-.C30)
 CALL CHNECT
 CALL CURVE (D1, WMG, 2, 0)
 CALL CURVE (D2, RLE, 2, 0)
 CALL DONEFL
 STOP
 ENC


```

DATA DVT2/2.07,2.44,2.65,2.77,2.83/
DATA DVT1/2.07,2.46,2.67,2.77,2.83/
DATA DVT4/2.07,2.47,2.69,2.81,2.89/
DATA DVT5/2.05,2.47,2.69,2.81,2.87/
DATA D1/2.52,2.9/
DATA WMG/2450.,2450./
DATA D2/2.36,2.52/
DATA RDB/2300.,2450./
DATA AR/2374.461,2390.2405.,2420.,2450./
DATA D3/2.44,2.65,2.75,2.745,2.78/

```

C
C
C

----- CALL DISSEFLA ROUTINES FOR PLOT -----

```

CALL TEK618
CALL MECEUF
CALL RESET (3HALL)
CALL HWSCAL ('SCREEN')
CALL PAGE (12.C, 9.5)
CALL GEACE (0.C)
CALL PHYSOR (1.0, 1.2)
CALL AREA2D (1C., 6.5)
CALL FRAME
CALL SWISSI
CALL BASALF ('L/CSTD')
CALL MIXALF ('STAND')
CALL INTAXS
CALL YTICKS (5)
CALL XTICKS (5)
CALL SHDCHR (.90, 1., .015, 1)
CALL HEIGHT (.16)
CALL XNAME ('(D)ISK (L)OADING', 100)
CALL YNAME ('(G)ROSS (H)EIGHT (LBS)', 100)
CALL HEIGHT (.290)
CALL HEADIN ('(H)ELICOPTER (C)ARPET (F)LOTS',
1 100, 1.0, 1)
CALL HEIGHT (.20)
CALL GRAF (2.C, .1, 3.C, 230C., 5C., 2550.)
IYGRID=5
CALL THKCRV (.C18)
CALL PARA3
CALL LEGLIN
CALL CURVE (D13, W3, 5, 0)
CALL CURVE (D14, W4, 5, 0)
CALL CURVE (D15, W5, 5, 0)
CALL CURVE (D16, W6, 5, 0)
CALL CURVE (D17, W7, 5, 0)
CALL DASE
CALL CURVE (DVT1, WVT1, 5, 0)
CALL CURVE (DVT2, WVT2, 5, 0)
CALL CURVE (DVT3, WVT3, 5, 0)
CALL CURVE (DVT4, WVT4, 5, 0)
CALL CURVE (DVT5, WVT5, 5, 0)
CALL THKCRV (.030)
CALL CHNDCT
CALL CURVE (D1, WMG, 2, 0)
CALL CURVE (D2, RDB, 2, 0)
CALL CURVE (D3, AR, 5, 0)
CALL DONEFL
STOP
END

```



```

C THIS PROGRAM IS DESIGN TO GENERATE THE DATA FOR THE GRAPHICAL
C SOLUTION OF THE WEIGHT AND THE USEFUL LOAD EQUATION. THIS IS THE
C FIRST STEP IN A CABRET FLOT HELICOPTER DESIGN PARAMETRIC OPTIMIZATION
C
C ASSUMPTIONS:
C 1> ENGINESPECIFIED
C VARIABLE OPTICNS
C
C REAL*4 CLR,PA,CL,K1,K2,K3,K4,K5,R,S,A,P,W(10),WB(10)
C INTEGER VT,D,I,CI
C
C-----
C CALL FRTCMS ('FILEDEF','02','DISK','CRPT1',
C >'DATA','A')
C-----
C CALL FRTCMS ('FILEDEF','03','DISK','CRPT2',
C >'DATA','A')
C-----
C
C CLR= DESIGN MEAN LIFT COEFFICIENT
C DC 90 CL=3.7
C CLR=CL*(C.1)
C WRITE(2,10)CLR
C PA= POWER AVAILABLE HP
C PA=206
C CL= DISK LOADING
C VT= TIP VELOCITY FT/SEC
C
C CONSTANTS BASED ON CLR
C
C K1=(0.9583)/CLR*(1+1.8078*CLR**2)
C K2=PA*10**5/K1
C K3=(0.0025929)/CLR*(1+1.8078*CLR**2)
C K4=553480.0/K1
C K5=3695.7/K1
C DC 100 D=200,300
C CL=D*(0.01)
C I=0
C DO 110 VT=600,700,25
C
C ARRAY INCREMENTER
C I=I+1
C WEIGHT EQUATION
C
C W(I)=(K2*(1-(411.51*DL**-.75)/(VT**1.5)*(1+K3*VT/DL**-.5)**-.5)-K4)
C 1/(VT+K5*DI**-.5)
C
C CALCULATION OF WE DATA
C
C A=W(I)/DI
C R=(A/3.14)**.5
C P=A**.5/VT
C S=(6.*DL)/(0.0023679*CLR*VT**2)
C
C ASSUMING A TEETERING SYSTEM
C
C WE(I)=1717.9+1221.*P**.863+266.*P**.7+17449./VT**1.14
C 1+2.886*A**.5*P**.57+.191*A(I)**.916+.0294*A(I)**.99
C 2+35.15*(W(I)/VT)*A**.185)*S**.33+.0088*W(I)*A**.21
C WRITE(5,20)VT
C WRITE(5,30)R
C 110 CONTINUE
C WRITE(2,31)DL,W(1),WE(1),W(2),WE(2)
C WRITE(3,31)CL,W(3),WB(3),W(4),WB(4),W(5),WB(5)
C 100 CONTINUE
C 90 CONTINUE
C
C FORMAT STATEMENTS
C 10 FORMAT ('1','CLR=',1F10.4///)
C 31 FORMAT ('6(2X,F10.3)')
C STOP
C END

```



```

C*****
C*****
C THIS PROGRAM IS DESIGNED TO OBTAIN THE GROSS WEIGHT FROM THE
C ASPECT RATIO GRAPH INTERSECTION POINT DATA. IN ORDER TO GRAPH
C THE ASPECT RATIO BOUNDARY ON THE MAIN CARPET PLOT A
C CORRESPONDING WEIGHT MUST BE OBTAINED. THIS PROGRAM UTILIZES
C THE WEIGHT ESTIMATION FORMULATION FROM THE CARPET PROGRAM.
C*****
C ASSUMPTIONS:
C 1> ENGINESPECIFIED
C*****
C VARIABLE OPTICNS
C REAL*4 VT(5),DL(5),CIR(5),W(5)
C DATA CLR/.625,.575,.535,.460,.42/
C DATA VT/600,625,650,675,700/
C DATA DL/2.75,2.75,2.72,2.67,2.53/
C-----
C CALL FRTCMS ('FILEDEF','03','DISK','CRPTAR',
C> 'DATA','A')
C-----
C
C DC 90 L=1,5
C WRITE(3,10) CLR(L)
C WRITE(3,20) VT(L)
C WRITE(3,30) DL(L)
C PA= POWER AVAILABLE HP
C PA=206
C EL= DISK LOADING
C VT= TIP VELOCITY FT/SEC
C
C CONSTANTS BASED ON CIR
C
C K1=(0.9583)/CLR(L)*(1+1.8078*CIR(L)**2)
C K2=PA*10**5/K1
C K3=(0.00025929)/CLR(L)*(1+1.8078*CLR(L)**2)
C K4=553480.0/K1
C K5=3695.7/K1
C WEIGHT EQUATION
C
C W(L)=(K2*(1-(411.51*DL(L)**.75)/(VT(L)**1.5)*
C 1*(1+K3*VT(L)/DL(L)**.5)**.5)-K4)/(VT(L)+K5*(DL(L)**.5))
C 90 WRITE(3,31) W(L)
C CONTINUE
C
C 10 FORMAT STATEMENTS
C 20 FORMAT ('1','CIR=',1F10.4///)
C 30 FORMAT ('2X','VT=',1F10.4///)
C 31 FORMAT ('2X','DL=',1F10.4///)
C STOP
C END

```


APPENDIX D. PROGRAMS TO ACCESS HESCOMP

This section contains the control language programs needed to access HESCOMP on the IBM main-frame computer.

024622-	1.105			
024851-	900.			
025310-	.80			
025422-2	3.			
02572140-				
0261140-				
026240-	0.4			
027240-5	.80			
031141130-	.75			
032310-				
032711-02				
032821-464	066.28			
033017-0				
033150-	0.2			
033321-0	1.4			
033355-06	.0062			
034422-012	.020			
260232200-	450.			
26053100-	0.			
260650-	0.			
261355-	25.			
2618430-	25.			
26225125-	.18			
262751-	2.08			
263251-0	0.			
2637544-2	.5			
264753-	2.2			
26522-17	14.2			
265451-0	250.			
265551-0	.17			
266451-0	1.0			
266951-0	1.0			
034753-0	1.0			
035430-0	3.0			
036131-0	0.5			
036831-0	1.0			
037531-0	1.0			
040110-	1.0			
04111-0333				
042110-				
04311-0				
04411-105				
046121-0				
048120-	1.0			
050120-	0.			
05120-	0.			
05212-06	1.06			
05312-02	1.02			
054121-105	1.105			
055121-1	1.			
057121-1	1.			
059120-	0.			
060120-	4			
061120-	0.			
06212200-	500.			
063122-	2			
06412500-	300.			
065121-105	1.105			
066126-	6			
067121-105	1.105			
068121-	1.			
069120-	0.			
070121-	1.			
071122-	4.			
072122-				
0731170-				
074130-	0.5			
075115	0.			
076130-	0.			
077135-	15.			
078132-	2			
079130-	100.			
080131-105	1.105			
081130-	0.			
082131-105	1.105			
083130-	0.			
024622-	10.			
024851-				
025310-				
025422-2				
02572140-				
0261140-				
026240-				
027240-5				
031141130-				
032310-				
032711-02				
032821-464				
033017-0				
033150-				
033321-0				
033355-06				
034422-012				
260232200-				
26053100-				
260650-				
261355-				
2618430-				
26225125-				
262751-				
263251-0				
2637544-2				
264753-				
26522-17				
265451-0				
265551-0				
266451-0				
266951-0				
034753-0				
035430-0				
036131-0				
036831-0				
037531-0				
040110-				
04111-0333				
042110-				
04311-0				
04411-105				
046121-0				
048120-				
050120-				
05120-				
05212-06				
05312-02				
054121-105				
055121-1				
057121-1				
059120-				
060120-				
061120-				
06212200-				
063122-				
06412500-				
065121-105				
066126-				
067121-105				
068121-				
069120-				
070121-				
071122-				
072122-				
0731170-				
074130-				
075115				
076130-				
077135-				
078132-				
079130-				
080131-105				
081130-				
082131-105				
083130-				

137551800.-	2000.-	2200.-	2600.-	5.-
138450.065	0.2	0.4	0.6	0.8
1390.065	-0.651	-0.653	-0.67	-0.71
1396.115	-116	-11E	-128	-14
1402.180	-181	-19	-208	-227
1408.26	-361	-362	-389	-325
1414.342	-435	-451	-486	-425
1420.5425	-511	-53	-56	-517
1426.5626	-631	-660.-	-718	-61
1433.41	-870.	1600.-	2600.-	-78
1447.43	0	0.49	0.8	
1454.30.26	0.271	0.49		
1460.30.82	0.84	0.90		
1466.31.09	1.118	1.165		
150251800.-	2000.-	2200.-	1400.-	1600.-
151250.29	0.265	0.471	0.628	5.-
152450.52	0.567	0.54	0.56	0.8
153050.6E	0.69	0.705	0.73	0.29
153650.82	0.824	0.84	0.868	0.59
154850.92	0.91	0.95	0.98	0.76
155451.052	1.005	1.07	1.05	0.90
156051.09	1.10	1.118	1.10	1.02
160123.074918	-9.02E	-262	1.135	1.131
16085.865	2.82	-0.9	-216	1.165
16095.079059	0.743	-0.04	1.17	2.45
161451.010	1.018	1.065	-0.07	-0.0124
162651.022	1.314	1.327	1.154	-0.09
16361.357	1.4	1.4	1.337	1.233
0001554	1.4	1.4	0.	1.364
001151	2.0000.-	2.0	1.	1.
001642	0.0	1.65	1.0	1.
002352	0.0	4.0	4.0	0.5
003551.0	0.0	3.0		2.0
003554.0	0.0			60.-
004354.0	0.0			
00471100.-	12	0.0	5	1.0
010350.50	-8	4.0	1.15	-12
011050.20	0.0	7.0	6.5	1.3
011950.102	1.2	0.	-55	5.-
012050.0	1.5	8	-85	5
013050.55	2.05	2.0E	0.	0.1
014050.180	2.0	-0.0E	-4	0.
014550.035	2	5		3.-
015151.4	1.0	1.2	0.75	1
017053.	-12	1.06	1.35	1000.-
0185725.	0.110	1.35	1.0	
0185543.53	0.	1.5	0.75	600.-
019131.53	1.0	1.65	1.00	-72
02085.17	2.0	1.0		
021331.00	2.0	1.0		
021910.761	2.0	1.0		
021932.0	2.0	1.0		
02235.96	2.0	1.0		
023350.0	2.0	1.0		
023841.105	2.0	1.0		
024211.761	2.0	1.0		
024511.0	2.0	1.0		

-70
0.

-60
0.
0.
0.
0.
1-105
1-5
1-105
0-0
0-0
0-0

08413-55
085130-
103120-
104120-4
105120-05
106120-05
107121-105
108121-5
109121-105
110120-0
11111-35
112120-0
113120-0
11611-1000-
11711-01
11811000-
119111-0
88888
59999
/*
//

APPENDIX E: HESCOMP INPUT AND OUTPUT EXAMPLES

This section contains samples of the IBM computer input and output.

HELICOPTER SIZING & PERFORMANCE COMPUTER PROGRAM E-

THE FOLLOWING IS A CARD BY CARD REPRODUCTION OF THE INPUT THIS CASE

LOC. CORRESPONDS TO LOCATION NUMBER GIVEN ON INPUT SHEET
 NUM STANDS FOR THE NUMBER OF SEQUENTIAL INPUT VALUES STARTINGLOC. (MAX. =5)
 VAL1 EQUALS VALUE FOR VARIABLE CORRESPONDING TO LOC.
 VAL2 VALUE CORRESPONDING TO LOC.+0001
 ETC. VALUE CORRESPONDING TO LOC.+0002

LOC.	NUM	VAL1	VA	VAL3	VAL4
1201	5	.0	.J	2.0000	.0
1206	1	.0	.C	32000E-01	950.00
1207	1	1.7610	2C0	2030.0	8.0000
1301	5	1.100.0	140	1600.0	1800.0
1306	1	870.00	260	5.0000	.0
1311	1	2000.0	.50	.00000	.0
1316	1	.0	.0	.0	.0
1321	1	.0	.0	.0	.0
1326	1	1.000	.18	20410	-23000
1332	1	3.000	.37	.41940	-48510
1338	1	5.400	.60	.63110	-78770
1344	1	7.700	.85	.96400	1.1150
1350	1	1.000	1.1	1.2520	1.4880
1356	1	1.000	1.1	1.5024	1.7376
1362	1	1.000	1.7	1.3406	2.2444
1368	1	8.000	1.0	1400.0	1600.0
1374	1	1800.0	220	2600.0	5.0000
1379	1	.0	.40	.03000	.80000
1384	1	.0	.65	.07000E-01	.71000E-01
1390	1	1.000	.11	12800	14000
1396	1	1.000	.19	20800	22700
1402	1	2.000	.27	29500	32500
1408	1	3.000	.36	38900	42500
1414	1	4.000	.45	48600	51700
1420	1	5.000	.53	58000	61000
1426	1	6.000	.66	71800	76000
1432	1	3.000	1.00	2600.0	.0
1438	1	3.000	.40	.80000	.0
1444	1	2.000	.29	.0	.0
1450	1	1.000	.90	.0	.0
1456	1	1.000	1.1	1400.0	1600.0
1462	1	1.000	1.3	2600.0	5.0000
1507	1	1800.0	220	2600.0	5.0000
1512	1	.0	.0	.0	.0
1518	1	.0	.0	.0	.0
1524	1	.0	.0	.0	.0
1530	1	.0	.0	.0	.0
1536	1	.0	.0	.0	.0
1542	1	.0	.0	.0	.0
1548	1	.0	.0	.0	.0
1554	1	.0	.0	.0	.0
1560	1	.0	.0	.0	.0
1566	1	.0	.0	.0	.0
1572	1	.0	.0	.0	.0

NOTE : IN USING AUXILIARY ENGINES : AUXILIARY ENGINE CYCLOCATIONS CAN BE CREATED
 BY PLACING A 66066 CARD IN FRONT AND BEHIND A STANDARD ENGINE

התורה והנבואה בלשון הקודש והתורה והנבואה בלשון חז"ל

[illegible][illegible]

16200E-01	-50000	7.0	6.5000	1.3000
1.0000	12.000	.0	-55000	5.3000
3.0000	1.1000			
4.0000	-15000			-500.0
18000E-01	-35000E-01	2.0	-85000	-10000
1.0000	2.3000	.78	-73000E-01	.0
3.0000	1.2000			
4.0000	-9.0000	1.50	-40000	3.0000
7.0000	12000	1.25	-75000E-01	10000
12000	1.1000	1.0	165.00	3000.0
1.0000	1.1000	1.7	1.3500	1.0000
1.0000	-4.0000	.65		
1.0000	1.7000	.30	-75000E-01	600.00
1.0000	1.0000	.75	1.0000	.72000
1.0	2.0000	1.0		
1.0	100.00	1.0	1.0000	4000.0
1.0	50.00	1.1	.0	-9500
2.0000	2.0000	3.0	170.00	43.200
.75000	.75000	.30	.0	
1.0	1.0000	10.	-75000E-01	-97000
1.0	3.0000			
1.0	20000	.40	-80000	.80000
1.0	8000	.60	1.0000	-95000E-02
1.0	5500	.75		
1.0	6.2800			
1.0	20000	-40	-60000	.80000
1.0	-60000E-02	-70	-80000E-02	
1.0	450.00	200		
1.0	25.000	.0	.0	.0
1.0	2.0000	.25	.0	.0
1.0	2.0000	2.40	80000	24.100
1.0	75000	1.0	-75000	.0
1.0	14.200	0.1	-2800	1.1500
1.0	250.00	2.0	1.0000	250.00
1.0	1.7000	2.0	1.0000	.11000
1.0	1.0000	1.0	1.0000	1.0000
1.0	1.0000	1.0	1.0000	1.0000
1.0	1.0000	1.0	1.0000	1.0000
1.0	3.0000	1.0	.50000	1.0000
1.0	1.0000	1.0		
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1.0	1.0000	1.0		
1.0	1.0000	1.0		
1.0	1.0000	1.0		
1.0				

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HELICOPTER SIZING & PERFORMANCE COMPUTER PROGRAM E-

SINGLE ROTOR CCFEOUND HELICOPTER AUX. INDEPENDENT I/SHAFT CRUISION

SIZE DATA THIS RUN CONVERGED IN 3 ITERATIONS

GROSS WEIGHT = 17043. LB

FUSELAGE

LENGTH(BODY+TAILBOOM) 50.1 FT.
LENGTH(CABIN) 12.0 FT.
LENGTH(BODY) 27.5 FT.
LENGTH(TAILBOOM) 22.8 FT.
WIDTH 15.1 FT.
WIDTH ROTOR LOCATION 8.3 FT.
WELDED AREA 717.5 SQ. FT.

WING

ASPECT RATIO 4.51
AREA 113.3 SQ. FT.
SPAN CHORD 22.8 FT.
QUARTER CHORD SWEEP 3.0 DEG.
TAPER RATIO 0.500
ROOT THICKNESS/CHORD 0.200
TIP THICKNESS/CHORD 0.120
WING LOADING 155.7 LBS/SQ. FT.
SECTION/WING GAP 3.6 FT.
FLAP CHORD/MEAN CHORD RATIO 1.300

HOB. TAIL

ASPECT RATIO 4.000
AREA 35.5 SQ. FT.
SPAN CHORD 11.9 FT.
TAPER RATIO 3.0 FT.
THICKNESS/CHORD 0.120
HOB. TAIL REM 26.0 FT.

VERT. TAIL

ASPECT RATIO 1.523
AREA 21.2 SQ. FT.
SPAN CHORD 5.7 FT.
TAPER RATIO 3.7 FT.
TAIL ROTOR/VERT. LOCATION 0.450
TAIL ROTOR/VERT. TAIL OVERLAP RATIO 0.900
THICKNESS/CHORD 0.150

HELICOPTER SIZING & PERFORMANCE COMPUTER PROGRAM E-

SINGLE ROTOR COMPOUND HELICOPTER AUX. INDEPENDENT 1/SHAFT CRUISE

SIZE DATA THIS RUN CONVERGED IN 3 ITERATIONS

GROSS WEIGHT = 17044. LB

FUSELAGE

LENGTH(BODY+TAILBOOM) 50.1 FT.
 LENGTH(CABIN) 12.0 FT.
 LENGTH(BODY) 27.5 FT.
 LENGTH(TAILBOOM) 22.0 FT.
 FWD. ROTOR LOCATION 15.1 FT.
 MID. 9.3 FT.
 REAR 737.5 SQ. FT.

WING

ASPECT RATIO 7.51
 AREA 111.3 SQ. FT.
 SPAN 30.0 FT.
 MEAN CHORD 3.7 FT.
 CHORD AT C/4 3.0 DEG.
 TAPER RATIO 0.500
 ROOT THICKNESS/CHORD 0.200
 TIP THICKNESS/CHORD 0.120
 WING LOADING 15.7 LBS/SQ. FT.
 LIFTING GAP 8.6 FT.
 FLAP CHORD/MEAN CHORD RATIO 1.300

HOR. TAIL

ASPECT RATIO 9.000
 AREA 35.5 SQ. FT.
 SPAN 11.9 FT.
 MEAN CHORD 3.0 FT.
 TAPER RATIO 0.500
 THICKNESS/CHORD 0.120
 PCB. TAIL ARM 20.0 FT.

VERT. TAIL

ASPECT RATIO 1.523
 AREA 21.2 SQ. FT.
 SPAN 5.7 FT.
 MEAN CHORD 3.7 FT.
 TAPER RATIO 0.450
 TAIL ROTOR(VERT.) LOCATION 4.0 FT.
 TAIL ROTOR/VERT. TAIL OVERLAP RATIO 0.900
 THICKNESS/CHORD 0.150

MAIN FCTCE EYLON

ASPECT RATIO 0.500
 WETTED AREA 19.1 SQ. FT.
 FRONTAL AREA 6.2 SQ. FT.
 HEIGHT 3.0 FT.
 MEAN CHORD 6.3 FT.
 TAPER RATIO 0.400
 FCOT THICKNESS/CHORD 0.400
 TIP THICKNESS/CHORD 0.200

PRIMARY ENGINE NACELLE

IN 5.3 FT.
 EN 2 FT.
 LENGTH 60.3 SQ. FT.
 MEAN DIAMETER
 WETTED AREA(TOTAL FOR ALL ENGINES)

AUXILIARY INDEPENDENT ENGINE NACELLE

IN 4.3 FT.
 EN 1 FT.
 LENGTH 19. SQ. FT.
 MEAN DIAMETER
 WETTED AREA(TOTAL FOR ALL ENGINES)

AUXILIARY INDEPENDENT ENGINE NACELLE STRUT

WETTED AREA(TOTAL) 0. SQ. FT.
 MEAN CHORD 0.1 FT.
 2.3 FT.

PROPELLER(AUXILIARY PROPULSION)

DIAMETER 10.3 FT.
 ACTIVITY FACTOR PER BLADE 140.3
 SOLIDITY 0.171
 NC. OF PROPELLERS 1
 NC. OF BLADES/PROP 3
 TIP SPEED 900. FT./SEC

MAIN FCTCE

CMR 45.2 FT.
 SIGR 0.128
 WG/A 11.13 LB/SQ. FT.
 CT/SIGMA C.110
 NB 1
 NC. BLADES 4
 THETA 1
 XC 1
 VTIE -9.00 DEG.
 0.250
 725. FT./SEC.

TAIL FCTCE

DIAMETER 10.3 FT.
 ACTIVITY FACTOR PER BLADE 140.3
 SOLIDITY 0.171
 NC. OF PROPELLERS 1
 NC. OF BLADES/PROP 3
 TIP SPEED 900. FT./SEC

3

100

WPE	WEIGHT OF PIXEL EQUIPMENT	2200.-
WE	WEIGHT EMPTY	11433.-
WPUL	PIXEL USEFUL LOAD	450.-
OWE	OPERATING WEIGHT EMPTY	11883.-
WPL	PAYLOAD	2000.-
(WF) A	FUEL	3760.-
WG	GROSS WEIGHT	17643.-

R O T O R D A T A

FOUR CYCLE NO. 3.0000

MAIN FACTOR SOLIDITY SIZED BY MANUEVER CONDITIONS
H = 1000.0 FT
100.0 PERCENT HOVER, RPM = 91.5 DEG. , V = KT.
FOUR MANUEVER G'S = 1.350 , CT/SIGMA = 0.110

TAIL FACTOR SIZED AT 1.050 TIMES THE SOLIDITY
REQUIRED TO SAILBY HOVERING TURN REQUIREMENTS AT
4000
= 95.0F,
CT/CTNET = 1.2
YAW RATE = 0.7EC
YAW ACCELERATION = 0.3EC2
TAIL ROTATION PERIOD = 4.1FT2
ACM UP INERTIA (PER BLADE) =
HELICOPTER YAW
MOM. OF INERTIA = 30385FT2

PRO P U L S I O N D A T A
PRIMARY PROPULSION CYCLE NO. 1-761
TURBOSHAP ENGINE

2. ENGINES

BHP*E	MAX. STANDARD S.L. STATIC H.P.	H.P.
ENGINE SIZED FOR TAKEOFF AT $1/W = 1.00$		
95.0 PERCENT MILITARY POWER SETTING,		
H = 4000. FT, TEMPERATURE = 95.04 DEG.F.,		
C.C. ENGINES INOPERATIVE, AND 0.0 FT/MIN VERTI OF CLIMB.		
AUX. INDEPENDENT PROPULSION CYCLE NO. 1-761		
TURBOSHAP ENGINE		

1. ENGINES

BHP*PI	MAX. STANDARD S.L. STATIC H.P.	H.P.
ENGINE SIZED FOR CRUISE AT VC = 170. KNOTS,		
ACRUAL POWER SETTING		
HC = 3000. FT, TEMPERATURE = 91.50 DEG.F.,		
AND 0.0 ENGINES INOPERATIVE.		

MAIN AND TAIL ROTOR DRIVE SYSTEM RATING H.P.

MAIN ROTOR DRIVE SYSTEM RATING 2914.

XMSN SIZED AT 100 PERCENT OF MAIN ROTOR HOVER POWER REQ
AT H = 4000. FT, TERE = 95.04 DEG.F., 100.0 PERCENT HOVER

TAIL ROTOR DRIVE SYSTEM RATING 436.

XMSN SIZED AT 100 PERCENT OF TAIL ROTOR HOVER POWER REQ
AT H = 4000. FT, TERE = 95.04 DEG.F., 100.0 PERCENT HOVER

AUXILIARY INDEPENDENT PROPULSION DRIVE SYSTEM RA 871. H.P.
XMSN SIZED AT 100 PERCENT OF AUX. PROPULSION CRUISE POWER AT VC = 170. KT,
HC = 3000. FT, TERE = 91.50 DEG.F.

HELICOPTER SIZING & PERFORMANCE COMPUTER PROGRAM

MISSION PERFORMANCE DATA

TIME (HRS)	TAXI FOR 0-C23			HPS. AT GROUND IDLE ENGINE RATING										FPM- ENG. CODE	TOTAL FUEL FLCWM (LBS/HR)	ALX. TURB. TEMP. (°R)	AUX. ENG. CODE	AUX. ENG. PERF	AUX. FULL FLCWM (LBS/HR)	TEMP. DEG. (°F)
	RANGE (N.M.)	FUEL USE (LBS)	WEIGHT (LBS.)	PRESS. ALT. (FT)	IAS (KTS)	PRIM. TURB. TEMP. (°R)	FPM- ENG. CODE	TOTAL FUEL FLCWM (LBS/HR)	ALX. TURB. TEMP. (°R)	AUX. ENG. CODE	AUX. ENG. PERF	AUX. FULL FLCWM (LBS/HR)	TEMP. DEG. (°F)							
0-C 0-C23	0-C C-C	0-C 14.6	17643 17628	C C	0-C C-C	950.0 950.0	I I	428 438	550.0 550.0	C-C	45 55	C-C	C-C	59.0 55.0						
TAKEOFF, POWER, CR LANO AT 1/W = 1-C6C FOR 0.100 HRS.																				
TIME (HRS)	RANGE (N.M.)	FUEL USE (LBS)	WEIGHT (LBS.)	PRES. ALT. (FT)	IAS (KTS)	PRIM. TURB. TEMP. (°R)	FPM- ENG. CODE	TOTAL FUEL FLCWM (LBS/HR)	ALX. TURB. TEMP. (°R)	AUX. ENG. CODE	AUX. ENG. PERF	AUX. FULL FLCWM (LBS/HR)	TEMP. DEG. (°F)							
														T-RPTCF RHP	VRC RHP	PRIM-ENG FUEL FLOW (LBS/HR)	AUX-ENG FUEL FLOW (LBS/HR)	RCILL CODE	DEELDGM	FMI
0-C23 0-C53	0-C C-C	14.6 65.0	17628 17598	0 C	1432 1429	1695.7 1684.2	P A	1527 1524	1-C6C 1-C60	0.705 0.705	2889 2881	0.0043 0.0043	0.073 0.066							
0-C23 0-C53	0-C C-C	14.6 65.0	17567 17537	C C	1427 1424	1682.8 1581.3	P A	1521 1519	1-C60 1-C60	0.705 0.705	2872 2864	0.0043 0.0043	0.073 0.066							
0-C23 0-C53	0-C C-C	14.6 65.0	17507 17476	0 C	1421 1418	1679.9 1678.5	P A	1516 1513	1-C60 1-C60	0.705 0.705	2856 2848	0.0043 0.0043	0.072 0.066							
0-C23 0-C53	0-C C-C	14.6 65.0	17476 17453	0 C	1418 1418	1678.5 1678.5	P A	1513 1513	1-C60 1-C60	0.705 0.705	2848 2848	0.0043 0.0043	0.072 0.066							

CRUISE AT SPEED FOR 99 PER CENT BEST RANGE WITH HEADWIND CF C.C

TIME (HRS)	RANGE (N.M.)	FUEL USED (LBS)	WEIGHT (LBS.)	PRE.S. ALT. (FT)	TAS (KTS)	PRIM. TURB. TEMP. (R)	PRIM. ENG. CCDE	CX	J	CP	CT	ALPHA C/L (DEG)	SPEC. RANGE (NM/HR)	BHP
M-ROTOR VTIP (FPS)	M-ROTOR RHP	T-ROTOR VTIP (FPS)	T-ROTOR RHP	PROP VTIP (FPS)	PRIM.ENG. FUEL FLOW (LBS/HR)	BHP AUX	ETAP FACP	LX. ENG. UEL FLOW (LBS/HR)	ENG. BHP OR TAKUST	AUX. TURB. TEMP.	AUX. ENG. CODE	AUX. ENG. PERF		
CPFR	CPINC	CPFR	CPNUD	CDO	DELCD	DELCDM								RN
0.597	67.55	645.5	16797.	5000.	149.1	1517.6	F	138.4	0.347	0.059		-2.8	11667	1877.
725.0	1416.	650.0	138.	---	994.	---	C.826	285.	1538.1	---		0.471	9.007	549.
0.000412	0.000052	C.CCC112	0.000054	0.01654	C.00021	0.00843	0.000371	---	---	---		C.500		3.781
0.688	82.55	574.1	16665.	5000.	145.1	1515.6	P	138.4	0.347	C.C55		-2.8	11700	1867.
725.0	1416.	650.0	107.	---	591.	---	0.826	285.	1537.1	---		0.471	0.007	546.
0.000410	0.000050	C.CCC112	C.000054	0.01647	C.00019	0.00837	C.000370	---	---	---		C.500		3.775
0.788	97.95	1102.2	16541.	5000.	149.1	1513.6	P	138.4	0.347	0.058		-2.3	11734	1856.
725.0	1416.	650.0	107.	---	987.	---	C.826	284.	1537.3	---		0.471	0.007	347.
0.000408	0.000048	C.CCC112	C.000053	0.01640	0.00013	0.00832	0.000370	---	---	---		C.500		3.778
0.899	112.55	1230.2	16413.	5000.	149.1	1511.6	P	138.4	0.347	C.C58		-2.5	11766	1846.
725.0	1416.	650.0	107.	---	984.	---	0.826	284.	1536.8	---		0.471	0.007	347.
0.000406	0.000046	C.CCC112	0.000053	0.01633	C.00017	0.00826	C.CCC370	---	---	---		C.500		3.776
0.969	127.95	1357.6	16285.	5000.	149.1	1509.7	F	138.4	0.347	0.057		-2.5	11759	1836.
725.0	1416.	650.0	106.	---	581.	---	0.826	284.	1536.4	---		0.469	0.007	546.
0.000405	0.000045	C.CCC112	C.000052	0.01626	0.00015	0.00821	0.000369	---	---	---		C.500		3.774
1.090	142.55	1484.8	16156.	5000.	149.1	1507.7	F	138.4	0.347	0.056		-2.5	11832	1826.
725.0	1416.	650.0	106.	---	577.	---	C.826	284.	1536.0	---		0.469	0.007	546.
0.000403	0.000043	C.CCC112	C.000052	0.01620	0.00014	0.00815	0.000369	---	---	---		C.500		3.772
1.137	150.00	1544.4	16095.	5000.	149.1	1506.8	P	138.4	0.347	0.056		-2.5	11847	1822.
725.0	1416.	650.0	106.	---	976.	---	C.826	284.	1535.7	---		0.468	0.007	545.
0.000402	0.000042	C.CCC112	C.000051	0.01610	0.00014	0.00813	0.000368	---	---	---		C.500		3.772

CLIMB TO 5000 FT WITH MAXIMUM R/C AT NORMAL ENGINE RATE
* TASIAND EAS) IS THE HORIZONTAL COMPONENT OF THE FLIGHT PATH

TIME (HRS)	RANGE (N.M.)	FUEL USED (LBS)	WEIGHT (LBS.)	PRES. ALT. (FT)	TAS (KTS)	PRIM. TURN TEMP. (R)	PRIM. ENG. CODE	DELCDM	CXR	J	CP	CT	ALPHA D/L (DEG)	GAMMA (DEG)	BHP	R/C (FPM)
M-ROTOR VTIP (FPS)	M-ROTOR RHP	T-RCTCK VTIP (FPS)	T-ROTOR RHP	PROF VTIP (FPS)	PRIM.ENG FUEL FLOW (LBS/HR)	BHP AUX	ETAP PRCP	DELCDM	CXR	U.S. ENG. FUEL FLOW (LBS/HR)	AUX. TURB. TEMP.	AUX. ENG. CODE	ALPHA D/L (DEG)	GAMMA (DEG)	BHP	R/C (FPM)
CPPRO	CP INC	OPPAR	CPNUD	CDU	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM	DELCDM
0.486	60.00	760.6	16882.	0.	76.4	1856.0	I	0.0000	0.0000	76.4	0.1856	0.063	-2.4	7.3	1949.	1012.
725.0	1141.	650.0	64.	---	890.	---	0.820	---	---	0.	---	---	0.835	0.007	0.959	---
0.494	60.44	768.0	16875.	500.	76.4	1856.0	I	0.0000	0.0000	75.9	0.1856	0.064	-2.3	7.1	1928.	976.
725.0	1123.	650.0	64.	---	885.	---	0.820	---	---	0.	---	---	0.837	0.007	0.960	---
0.503	61.30	775.5	16868.	1000.	76.4	1856.0	I	0.0000	0.0000	75.3	0.1856	0.065	-2.3	6.8	1907.	935.
725.0	1135.	650.0	64.	---	874.	---	0.820	---	---	0.	---	---	0.838	0.007	0.960	---
0.512	61.99	783.2	16860.	1500.	77.4	1856.0	I	0.0000	0.0000	75.7	0.1856	0.066	-2.3	6.5	1887.	902.
725.0	1139.	650.0	64.	---	864.	---	0.820	---	---	0.	---	---	0.840	0.007	0.960	---
0.521	62.71	791.3	16853.	2000.	77.4	1856.0	I	0.0000	0.0000	75.2	0.1856	0.067	-2.3	6.2	1866.	864.
725.0	1132.	650.0	64.	---	853.	---	0.820	---	---	0.	---	---	0.841	0.007	0.960	---
0.531	63.47	799.5	16844.	2500.	77.4	1856.0	I	0.0000	0.0000	74.6	0.1856	0.068	-2.3	5.9	1849.	825.
725.0	1135.	650.0	64.	---	842.	---	0.820	---	---	0.	---	---	0.842	0.007	0.961	---
0.541	64.26	808.0	16835.	3000.	78.4	1856.0	I	0.0000	0.0000	75.0	0.1856	0.069	-2.3	5.6	1825.	786.
725.0	1140.	650.0	64.	---	832.	---	0.820	---	---	0.	---	---	0.843	0.007	0.960	---
0.551	65.11	816.8	16826.	3500.	78.4	1856.0	I	0.0000	0.0000	74.5	0.1856	0.070	-2.3	5.3	1804.	747.
725.0	1144.	650.0	64.	---	821.	---	0.820	---	---	0.	---	---	0.844	0.007	0.961	---
0.561	65.99	826.0	16817.	4000.	79.4	1856.0	I	0.0000	0.0000	74.8	0.1856	0.071	-2.3	5.0	1787.	707.
725.0	1149.	650.0	64.	---	811.	---	0.820	---	---	0.	---	---	0.847	0.007	0.961	---
0.574	66.94	835.5	16807.	4500.	79.4	1856.0	I	0.0000	0.0000	74.3	0.1856	0.072	-2.3	4.7	1763.	666.
725.0	1153.	650.0	64.	---	801.	---	0.820	---	---	0.	---	---	0.849	0.007	0.961	---
0.587	67.95	845.5	16797.	5000.	79.4	1856.0	I	0.0000	0.0000	73.7	0.1856	0.073	-2.3	4.4	1743.	626.
725.0	1156.	650.0	64.	---	790.	---	0.820	---	---	0.	---	---	0.850	0.007	0.962	---
0.600	69.00	856.0	16787.	5500.	79.4	1856.0	I	0.0000	0.0000	73.2	0.1856	0.074	-2.3	4.1	1723.	586.

CHANGE PAYLOAD,	REC'D	ICCO.	LE.	
TIME	RANGE	FUEL	WEIGHT	PRES.
(HRS)	(K.M.)	USED	(LB.)	ALT.
1.337	130.00	1820.2	14823	(FT)
1.347	130.00	1820.2	14823	1000.
				1000.

LCITER FOR C.SCC HRS.

TIME (HRS)	RANGE (N.M.)	FUEL (LBS)	WEIGHT (LBS.)	PRES. ALT. (FT)	TAS (KTS)	PRIM. TURB. TEMP. (R)	PRIM. ENG. CCLC	FAS (KTS)	MU	CT OVER SIGMA	ALPHA D/L (DEG)	TOTAL FUEL (LBS/HK)	DHP
M. RCTCR VTIP (FPS)	M. RCTCR RHP	T. RCTCR VTIP (FPS)	T. RCTCR RHP	PROP VTIP (FPS)	PRIM. ENG FUEL FLOW (LBS/HK)	BHP AUX	ETAP PRCP	LX. ENG. FUEL FLOW (LBS/HK)	AUX. TURB. TEMP.	ALX. ENG. CCLC	AUX. ENG. PEHF	AUX. BHP GR	AUX. BHP HPRUST
CPHRC	CPINE	CPFR	CPAUD	CDU	DELCD	DELCD	CXR	J	CP	CT	CLW	CDL	RII
1:247 725.0 0.000150	150.00 500.0 0.000162	1820.2 650.0 C.CCC033	14823. 51. 0.000005	1000. 0.000022	75.6 813. 0.00039	1375.0 0.00039	P 0.000183	74.5 155. ---	0.176 1201.7 ---	0.056 P ---	-1.5 0.044 0.400	961. 0.007 ---	1093. 55. 0.942
1:257 725.0 0.000150	150.00 500.0 0.000162	1820.2 650.0 C.CCC033	14774. 51. 0.000005	1000. 0.000022	75.6 812. 0.00038	1374.4 0.00038	P 0.000183	74.5 155. ---	0.176 1201.7 ---	0.056 P ---	-1.5 0.044 0.400	961. 0.007 ---	1093. 55. 0.942
1:247 725.0 0.000150	150.00 500.0 0.000158	1820.2 650.0 C.CCC033	14726. 51. 0.000005	1000. 0.000022	75.6 811. 0.00038	1373.8 0.00038	P 0.000183	74.5 155. ---	0.176 1201.7 ---	0.056 P ---	-1.5 0.044 0.400	961. 0.007 ---	1087. 55. 0.942
1:257 725.0 0.000150	150.00 500.0 0.000158	1820.2 650.0 C.CCC033	14678. 51. 0.000005	1000. 0.000022	75.6 810. 0.00038	1372.2 0.00038	P 0.000183	74.5 155. ---	0.176 1201.7 ---	0.056 P ---	-1.5 0.044 0.400	961. 0.007 ---	1082. 55. 0.942
1:247 725.0 0.000150	150.00 500.0 0.000156	1820.2 650.0 C.CCC033	14630. 51. 0.000005	1000. 0.000022	75.6 809. 0.00038	1372.6 0.00038	P 0.000183	74.5 155. ---	0.176 1201.7 ---	0.055 P ---	-1.5 0.044 0.400	961. 0.007 ---	1080. 55. 0.942
1:257 725.0 0.000150	150.00 500.0 0.000156	1820.2 650.0 C.CCC033	14581. 51. 0.000005	1000. 0.000022	75.6 808. 0.00038	1372.0 0.00038	P 0.000183	74.5 155. ---	0.176 1201.7 ---	0.055 P ---	-1.5 0.044 0.400	961. 0.007 ---	1077. 55. 0.941
1:247 725.0 0.000150	150.00 500.0 0.000154	1820.2 650.0 C.CCC032	14533. 51. 0.000005	1000. 0.000022	75.6 807. 0.00038	1371.4 0.00038	P 0.000182	74.5 155. ---	0.176 1201.7 ---	0.055 P ---	-1.5 0.044 0.400	961. 0.007 ---	1074. 55. 0.941
1:257 725.0 0.000150	150.00 500.0 0.000154	1820.2 650.0 C.CCC032	14485. 51. 0.000005	1000. 0.000022	75.6 806. 0.00038	1370.8 0.00038	P 0.000182	74.5 155. ---	0.176 1201.7 ---	0.055 P ---	-1.5 0.044 0.400	961. 0.007 ---	1070. 55. 0.941
1:247 725.0 0.000149	150.00 500.0 0.000155	1820.2 650.0 C.CCC031	14437. 51. 0.000005	1000. 0.000022	74.6 805. 0.00035	1370.5 0.00035	P 0.000179	73.5 154. ---	0.174 1201.2 ---	0.055 P ---	-1.5 0.042 0.400	958. 0.007 ---	1068. 53. 0.942
1:257 725.0 0.000149	150.00 500.0 0.000154	1820.2 650.0 C.CCC031	14389. 51. 0.000005	1000. 0.000022	74.6 804. 0.00035	1369.9 0.00035	P 0.000178	73.5 154. ---	0.174 1201.2 ---	0.055 P ---	-1.5 0.042 0.400	958. 0.007 ---	1065. 53. 0.942
1:247 725.0 0.000149	150.00 500.0 0.000153	1820.2 650.0 C.CCC031	14341. 51. 0.000005	1000. 0.000022	74.6 803. 0.00034	1369.3 0.00034	P 0.000178	73.5 154. ---	0.174 1201.2 ---	0.054 P ---	-1.5 0.042 0.400	957. 0.007 ---	1061. 53. 0.942

CLIMB TC 3000 FT WITH MAXIMUM R/C AT NORMAL ENGINE RAT
 TAS (AND EAS) IS THE HORIZONTAL COMPONENT OF THE FLIGHT PATH

TIME (HRS)	RANGE (N.M.)	FUEL USED (LBS)	WEIGHT (LBS.)	PRES. ALT. (FT)	TAS (KTS)	PRIM. TEMP. (R)	ENG. CODE	EAS (KTS)	MU	CT OVER SIGMA	ALPHA D/L (DEG)	GAMMA (DEG)	BHP	R/C (FPM)
M. RCTCR VTIP (EFS)	M. RCTCR RHP	T. RCTCR VTIP (EFS)	T. RCTCR RHP	PROF VTIP (EFS)	PRIM. ENG. FUEL FLOW (LBS/HR)	BHP AUX	ETAP FRCP	UX. ENG. UEL FLOW (LBS/HR)	AUX. TURB. TEMP.	AUX. ENG. CODE	AUX. ENG. PEHF			
CPERC	CPINC	CPPAR	CPNUD	CD0	DELCDS	DELCDM	CAR	J	CP	CT	CLW	CDW	RN	
1.847 725.0 0.000147	150.00 543. 0.000159	2301.6 650.0 0.000159	14341. 56. 0.000000	1000. --- 0.00013	71.5 874. 0.0	1856.0 --- 0.00030	I C.820 0.000317	70.5 0. ---	0.165 1856.0 ---	0.055 --- ---	-2.6 0.838 0.400	11.0 0.007 0.007	1905. 0.943 0.943	1469.
1.853 725.0 0.000147	150.41 543. 0.000164	2306.6 650.0 0.000164	14336. 57. 0.000000	1500. --- 0.00015	71.5 863. 0.0	1856.0 --- 0.00033	I 0.820 0.000318	69.9 0. ---	0.169 1856.0 ---	0.055 --- ---	-2.6 0.840 0.400	11.0 0.007 0.007	1849. 0.940 0.940	1429.
1.859 725.0 0.000149	150.83 545. 0.000166	2311.6 650.0 0.000166	14331. 57. 0.000000	2000. --- 0.00020	72.5 852. 0.0	1856.0 --- 0.00038	I C.820 0.000326	70.4 0. ---	0.171 1856.0 ---	0.056 --- ---	-2.6 0.841 0.400	10.6 0.007 0.007	1809. 0.943 0.943	1389.
1.865 725.0 0.000149	151.28 546. 0.000171	2316.7 650.0 0.000171	14326. 57. 0.000000	2500. --- 0.00023	72.5 842. 0.0	1856.0 --- 0.00041	I C.820 0.000327	69.9 0. ---	0.171 1856.0 ---	0.057 --- ---	-2.6 0.843 0.400	10.0 0.007 0.007	1843. 0.940 0.940	1349.
1.871 725.0 0.000150	151.73 547. 0.000177	2321.5 650.0 0.000177	14321. 56. 0.000000	3000. --- 0.00026	72.5 831. 0.0	1856.0 --- 0.00044	I C.820 0.000328	69.4 0. ---	0.171 1856.0 ---	0.058 --- ---	-2.5 0.844 0.400	10.0 0.007 0.007	1823. 0.947 0.947	1308.

CRUISE AT SPEED FOR 99 PER CENT BEST RANGE WITH HEADWIND OF C.C

TIME (HRS)	RANGE (N.M.)	FUEL (SEC) (LBS)	WEIGHT (LBS.)	PRES. ALT. (FT)	TAS (KTS)	PRIM. TURB. TEMP. (R)	PRIME ENG. CODE	CT	PRIME SIGMA	ALPHA D/L (DEG)	SPEC. RANGE (LMP)	BHP	
M-RTCR VTRP (FPS)	M-RTCR RHP	T-RTCR VTRP (FPS)	T-RTCR RHP	PROF VTRP (FPS)	PRIM-ENG FUEL FLOW (LBS/HR)	PHP AUX	ETAP PFOP	ALX. TURB. TEMP.	MU	EAS (KTS)	UX, ENG. FLW (LBS/HR)	AUX. ENG. PFTF	
CPPRO	CPINC	CPFAR	CPNUO	COO	DELCUS	OELCDM	CXR	J	CP	CI	CLW	CDW	RN
1-271 725.0 0.000361	151.73 0.000350	2321.5 0.000350	14321.5 0.000350	3000.0 0.01443	150.1 0.00031	1460.1 0.00652	P 0.000273	143.6 33.5	C-345 1609.1	C-044 ---	-2.8 0.500	.11017 0.007	1613. 672.5
1-571 725.0 0.000360	146.73 0.000349	2448.5 0.000349	14194.5 0.000349	3000.0 0.01438	150.1 0.00031	1458.7 0.00647	P 0.000273	143.6 33.5	C-345 1603.1	C-044 ---	-2.8 0.500	.11842 0.007	1605. 672.5
2-071 725.0 0.000355	181.73 0.000348	2515.5 0.000348	14067.5 0.000348	3000.0 0.01434	150.1 0.00031	1457.3 0.00643	P 0.000273	143.6 33.5	C-345 1608.2	0.043 ---	-2.8 0.500	.11867 0.007	1597. 671.8
2-171 725.0 0.000357	196.73 0.000347	2701.5 0.000347	13941.5 0.000347	3000.0 0.01429	150.1 0.00031	1455.9 0.00639	P 0.000272	143.6 33.5	C-345 1607.1	0.042 ---	-2.8 0.500	.11852 0.007	1590. 670.5
2-271 725.0 0.000356	211.73 0.000345	2828.5 0.000345	13815.5 0.000345	3000.0 0.01425	150.1 0.00030	1454.6 0.00634	P 0.000272	143.6 33.5	C-345 1607.2	C-042 ---	-2.8 0.500	.11917 0.007	1582. 670.8
2-371 725.0 0.000355	226.73 0.000344	2953.5 0.000344	13685.5 0.000344	3000.0 0.01420	150.1 0.00030	1453.2 0.00630	P 0.000272	143.6 33.3	C-345 1606.8	C-041 ---	-2.8 0.500	.11541 0.007	1575. 669.3
2-471 725.0 0.000354	241.73 0.000343	3078.5 0.000343	13562.5 0.000343	3000.0 0.01416	150.1 0.00030	1451.9 0.00626	F 0.000271	143.6 33.3	C-345 1606.3	0.041 ---	-3.0 0.500	.11568 0.007	1568. 668.3
2-571 725.0 0.000353	256.73 0.000342	3204.5 0.000342	13438.5 0.000342	3000.0 0.01412	150.1 0.00030	1450.6 0.00622	F 0.000271	143.6 33.3	C-349 1605.8	C-040 ---	-3.0 0.500	.11550 0.007	1561. 667.3
2-670 725.0 0.000352	271.73 0.000341	3330.5 0.000341	13312.5 0.000341	3000.0 0.01408	150.1 0.00030	1449.3 0.00617	P 0.000271	143.6 33.3	C-349 1605.3	C-040 ---	-3.0 0.500	.12015 0.007	1553. 667.3
2-770 725.0 0.000351	286.73 0.000340	3454.5 0.000340	13186.5 0.000340	3000.0 0.01403	150.1 0.00030	1448.0 0.00613	P 0.000271	143.6 33.2	C-345 1604.5	0.039 ---	-3.1 0.500	.12038 0.007	1546. 666.3
2-859 725.0 0.000350	300.00 0.000339	3585.5 0.000339	13078.5 0.000339	3000.0 0.01400	150.1 0.00030	1446.9 0.00610	P 0.000270	143.6 33.2	C-345 1604.5	0.039 ---	-3.1 0.500	.12060 0.007	1540. 665.3

LCITER FOR C-250 FKS. FOR RESERVE FUEL

TIME (HRS)	RANGE (N.M.)	FUEL (LBS)	WEIGHT (LBS.)	PRES. ALT. (FT)	IAS (KTS)	PRIM. TURB. TEMP. (R)	PRIM. ENG. CODE	EAS (KTS)	MU	CT PRIME OVER SIGMA	ALPHA D/L (CEG)	TOTAL FUEL (LBS/HK)	BHP
M. ROTOR VTP (FPS)	M. ROTOR RHP	1-2-CT VTP (FPS)	T. ROTOR RHP	PROP VTP (FPS)	PRIM. ENG. FUEL FLOW (LBS/HK)	BHP AUX	ETAP PRCP	UX. ENG. FUEL FLOW (LBS/HK)	AUX. TURB. TEMP.	ENG. CODE	ALX. ENG. PEHF		AUX. BHP THRUST
CPFRD	CPINC	CPRAR	CPNUD	CDU	DELCDU	DELCDM	CXR	J	CP	CT	CLW	CUM	RN
2.555 725.0 C.000146	300.00 841. C.000146	2565.0 650.0 C.000045	13075. 53. C.000008	3000. --- 0.00820	73.1 754. 0.0	1361.3 --- 0.00037	F C.835 C.000264	69.9 78. ---	0.170 852.1 ---	0.053 P ---	-2.2 0.0 C.400	835. 0.007 0.007	1022. 0. 0.943
2.555 725.0 C.000146	300.00 839. C.000145	2606.5 650.0 C.000045	13036. 53. C.000008	3000. --- 0.00820	73.1 757. 0.0	1360.9 --- 0.00037	F C.835 C.000264	69.9 78. ---	0.170 852.1 ---	0.052 P ---	-2.3 0.0 C.400	835. 0.007 0.007	1019. 0. 0.942
2.555 725.0 C.000146	300.00 836. C.000144	2648.6 650.0 C.000045	12994. 53. C.000008	3000. --- 0.00820	73.1 756. 0.0	1360.3 --- 0.00036	P C.835 C.000263	69.9 78. ---	0.170 852.1 ---	0.052 P ---	-2.3 0.0 C.400	834. 0.007 0.007	1017. 0. 0.942
3.009 725.0 C.000146	300.00 831. C.000143	2650.2 650.0 C.000045	12953. 53. C.000008	3000. --- 0.00820	73.1 755. 0.0	1355.7 --- 0.00036	P C.835 C.000263	69.9 78. ---	0.170 852.1 ---	0.052 P ---	-2.3 0.0 C.400	833. 0.007 0.007	1014. 0. 0.942
3.055 725.0 C.000146	300.00 831. C.000142	2711.5 650.0 C.000045	12911. 53. C.000008	3000. --- 0.00820	73.1 753. 0.0	1359.2 --- 0.00036	P C.835 C.000263	69.9 78. ---	0.170 852.1 ---	0.052 P ---	-2.3 0.0 C.400	832. 0.007 0.007	1011. 0. 0.942
3.109 725.0 C.000147	300.00 828. C.000144	2773.5 650.0 C.000044	12865. 53. C.000007	3000. --- 0.00817	72.1 754. 0.0	1358.6 --- 0.00034	P C.835 C.000268	69.0 78. ---	0.168 852.1 ---	0.052 P ---	-2.2 0.0 C.400	831. 0.007 0.007	1008. 0. 0.943

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